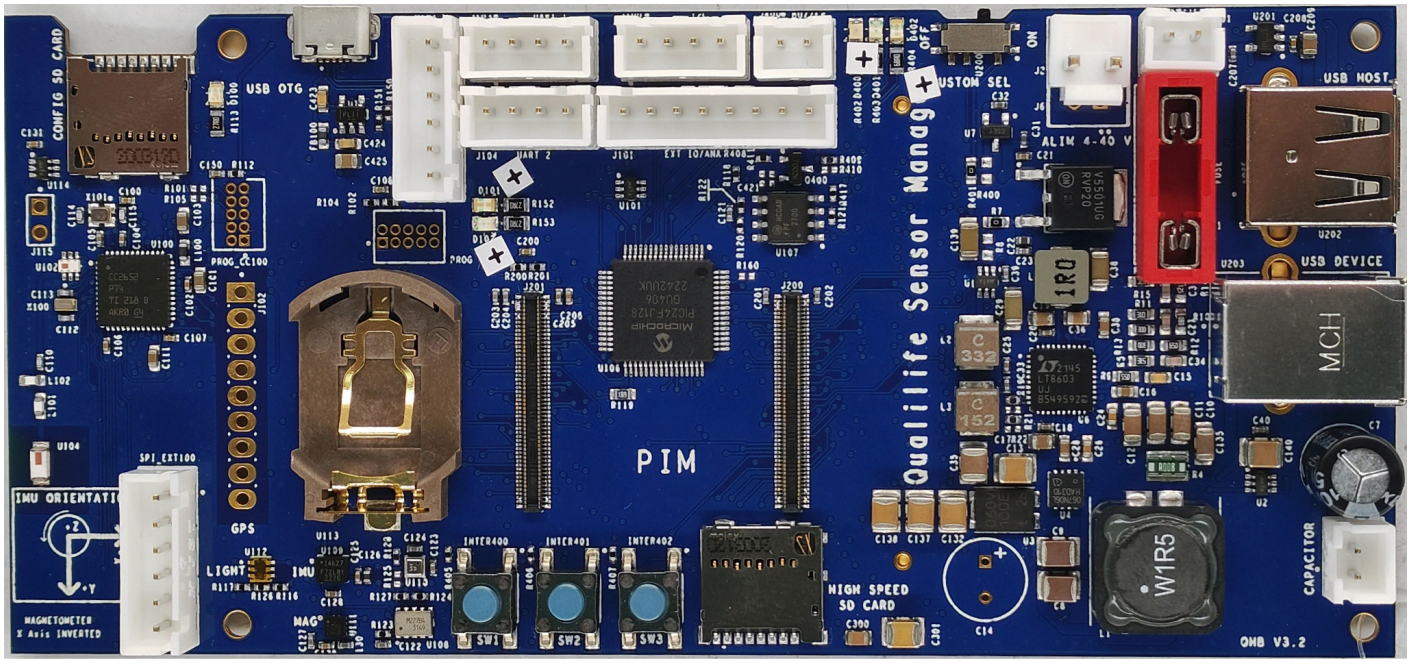
ACOUSTIC ACQUISITION SYSTEM

QUALILIFE HIGHBLUE V3.0



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FEATURES

ACQUISITION:

- Acquisition Sample Rate: Up to 512 Ksps
- Frequency range of the input signal: 0.5 Hz to 256 kHz.
- Acquisition resolution in 8, 16, or 24 bits adjustable via a configuration script.
- Differential acquisition with 2.5V maximum input level.
- Accurate timestamping
- Anti-aliasing filter configurable to input signal without change of input signal in the passband (see section « characteristic of Anti-Aliasing filters »).

AMPLIFIER :

- Differential amplifier
- Amplifying the signal from the hydrophone: X1, X10, X20, X100
- Single ended input and differential output
- Input impedance: 10 ^ 13 ohm.
- Input Filter: First order High-Pass filter : Cutoff frequency = 0.96Hz

STORAGE:

- Storage support on micro SD card (or SD via an adapter)
- Storage support on USB MSD (USB Flash Drive, HDD, SCSI)
- Storage support on PC (USB Device Mode)

MOTION:

- Integrate Inertial motion sensor (6DoF)
- Integrate high Precision Magnetometer

OTHER:

- Integrate Light Sensor (IR+Visible)
- Integrate Pressure and Temperature Sensor
- Allow GPS Support

WIRELESS:

- Integrate a BLE 4.0 chip that allow user to monitor/configure system

POWER SUPPLY:

- Power Supply range: From 4V to 40VDC

ENERGY CONSUMPTION :

- Max Power Consumption: 4W in lifelong learning (SD and hydrophone including C75, X5 channels)
- Max Power consumption: 100µW in Sleep Mode

PROCESSING:

- Support embedded processing by deep Learning

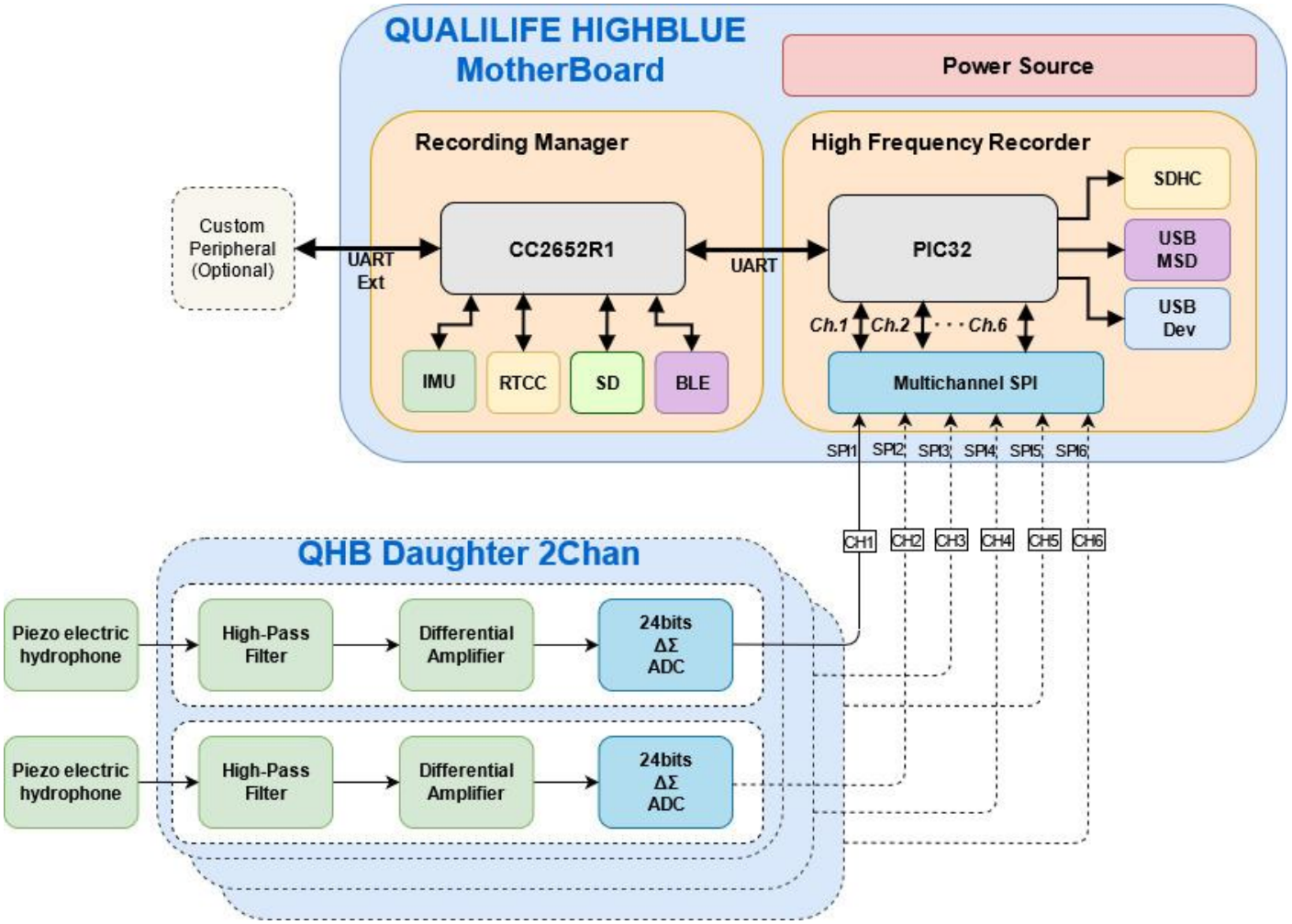
SPECIAL FEATURES:

- Allow synchronization on PPS if using GPS. (50ns jitter)
- Support synchronization by atomic clock
- Allow Processor change to reduce overall consumption if no high Frequency recording is required.

APPLICATIONS

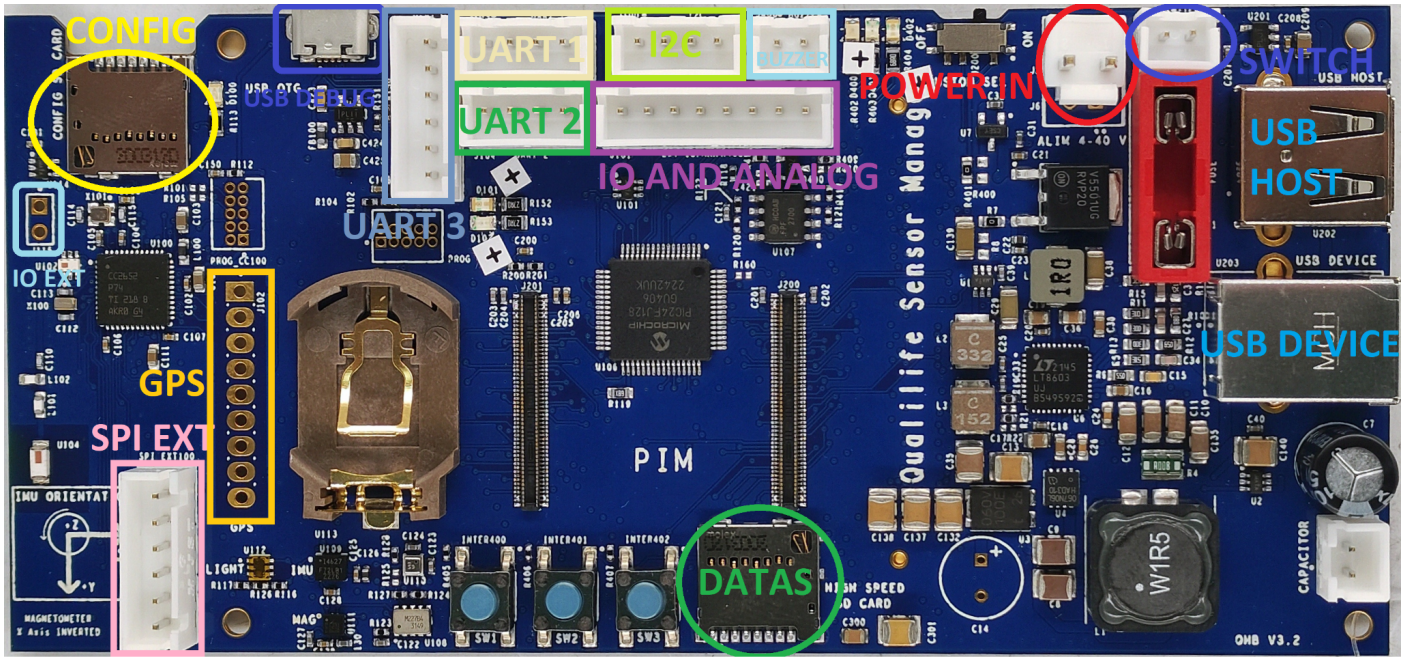
- Vibration and Modal Analysis
- Data Acquisition Systems
- Acoustics and Dynamic Strain Gauges
- Power Quality Analysis
- Long Term Monitoring
- 3D Tracking of source
- Motion tracking

QHB Block Diagram



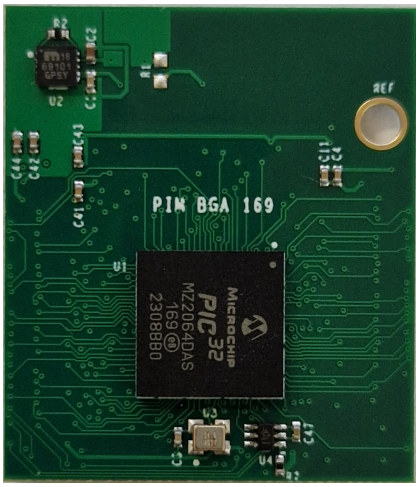
Connectors Description

On Motherboard:



PIM (Plug In Module) (J200, J201):

These two connectors are used to plug the main processor of QHB Motherboard. This allows the customer to change the processor depending on the application. For example if high computation power is required, a powerful processor can be used, otherwise, a smaller processor can be used to reduce cost and power consumption.

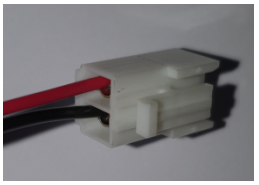


POWER Connector (J2/J6:"POWER IN")

This Connector is the POWER Connector. It is used to provide power to the board.

It use a JST connecto (J2)r: ***B2P-VH(LF)(SN)*** or ***B2B-XH-A(LF)(SN)*** for J6

The cable to use to power the system have to be a JST: ***VHR-2N***



PIN	FUNC
1	+VCC
2	GND

The voltage (**VCC**) should be at least **4V**, up to **40V DC**

External SWITCH Connector (J1: "Switch")

This connector is used to close or open the power circuit. If not used, connect the two pin together (with a jumper).

It use a JST connector: ***B2B-XH-A(LF)(SN)***

The cable to use to connect the switch to the system have to be a JST: ***XHP-2***

PIN	FUNC
1	VCC_IN
2	VCC_OUT

External Capacitor (J3:"CAPA") [Optional]

To avoid power loss at light impacts or movements (when used in a sealed tube), a decoupling capacitor has been added to the system. This must be connected to the capture card to ensure proper operation thereof.

It use a JST connector: ***B2B-XH-A(LF)(SN)***

The cable to use to connect the capacitor to the system have to be a JST: ***XHP-2***

PIN	FUNC
1	+VCC
2	GND

CR2032 Connector (U109)

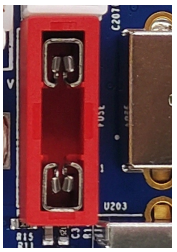
The system has a holder for a CR2032 for saving and maintenance of the internal clock for a period of 10 to 15 years in the case of cutoff of the power supply. This battery will be necessary to maintain the time of day system (Main Switch Off), or in the case of too low power (low battery, ...).

Fuse Connector (Fuse)

The system has a holder for a fuse to protect the system against over-current.

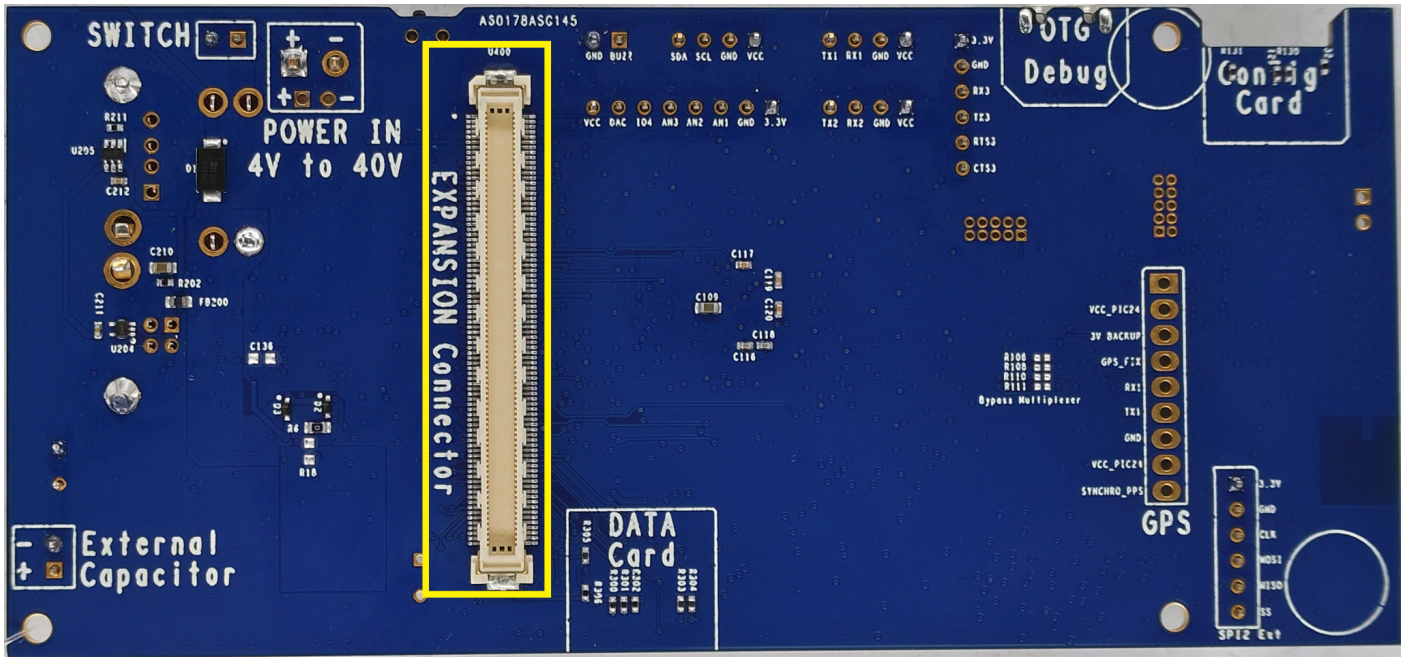
We recommend using a 2A fuse. (for example: Littelfuse 2A (0891002.H))

Low profile fuse can be used, and are recommended to minimize the height of the board.



Extension Connector (U400)

There is an extension connector, used to stack multiple daughter boards to the motherboard.



This is a 168 pin connector.

Uart 1 Connector

This Connector is used to connect a GPS to QHB.

It use a JST connector: ***B4P-XH(LF)(SN)***

The cable to use to power the system have to be a JST: ***XHP-4***

PIN	FUNC
1	+3.3V Always ON
2	GND
3	Rx1
4	Tx1

UART 2 CONNECTOR

This Connector is used to connect a GSM to QHB. (Used in MARITIMO)

It use a JST connector: ***B4P-XH(LF)(SN)***

The cable to use to power the system have to be a JST: ***XHP-4***

PIN	FUNC
1	+3.3V Always ON
2	GND
3	Rx2
4	Tx2

UART 3 CONNECTOR

This Connector is used to connect an external system to QHB. (For example a Buoy in MARITIMO)

It is different compared to UART 1 and UART 2, as it can be used with Flow Control to reach speeds up to 2Mbps.

It use a JST connector: ***B6P-XH(LF)(SN)***

The cable to use to connect the uart3 to the system have to be a JST: ***XHP-6***

PIN	FUNC
1	+3.3V Always ON
2	GND
3	Rx3
4	Tx3
5	RTS3
6	CTS3

I2C Connector

This connector can be used to connect external sensors to QHB. (for example an hygrometer, or a PH Meter).

It use a JST connector: ***B4P-XH(LF)(SN)***

PIN	FUNC
1	+3.3V Always ON
2	GND
3	SCL
4	SDA

GPS Connector (J102)

This Connector is used to connect a GPS to QHB [Optional]. (such as Ultimate GPS from Adafruit©).

It uses the same signal as UART1, so special care should be taken when using it, as UART1 will not be available.

The pin description follow:

PIN	FUNC	Description
1	GPS_DETECT	This allow the system to detect GPS Module
2	ENABLE_GPS	This pin is used by QHB to enable GPS.
3	3V_BACKUP	This is a 3V backup supply provided from QHB.
4	GPS_FIX	This indicate to QHB that the GPS is Fixed.
5	RX1	RX from QHB
6	TX1	TX from QHB
7	GND	Ground
8	3.3V	3.3V from QHB to power GPS Module
9	SYNCHRO_PPS	1 Pulse per Second output from GPS (50ns Jitter) used to synchronize QHB Clocks.

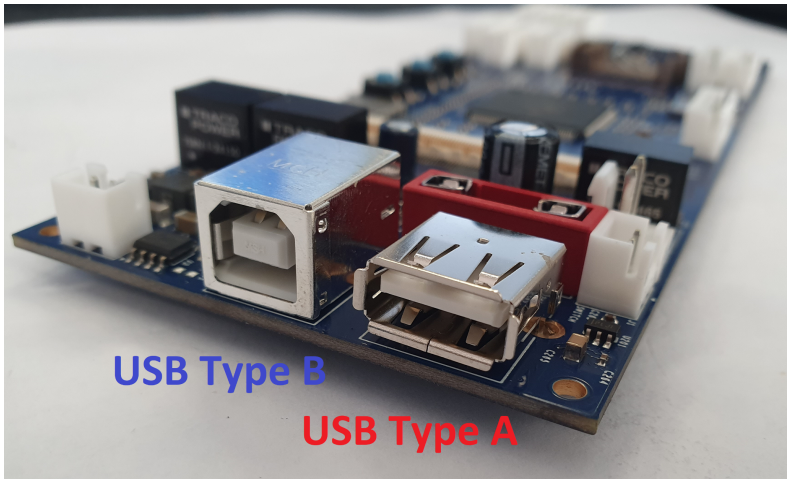
External IO/Analog Connector (J101)

This Connector allows the user to connect a custom sensor/analog/IO Pin to QHB. (Not implemented yet).

The pin description follow:

PIN	FUNC	Description
1	3.3V Always ON	3.3V Always ON from QHB
2	GND	Ground.
3	ANA_1	This is analog input pin, or Digital IO (in/out)
4	ANA_2	This is analog input pin, or Digital IO (in/out)
5	ANA_3	This is analog input pin, or Digital IO (in/out)
6	IO_4	This is Digital IO (in/out)
7	DAC_OUT	This is analog output pin, or Digital IO (in/out)
8	3.3V	3.3V from QHB (Turned OFF in Sleep)

USB Connectors



Note: Do not connect USB type A and USB Type B at the same time!!

USB HOST Connector

The USB Host Connector (USB type A) allows the user to plug a USB Flash drive or HDD/SSD to QHB as a storage device for datas.

In this case, the QHB operates as “Host”, and will write data on the storage media plugged to the USB type A slot.

USB Device Connector

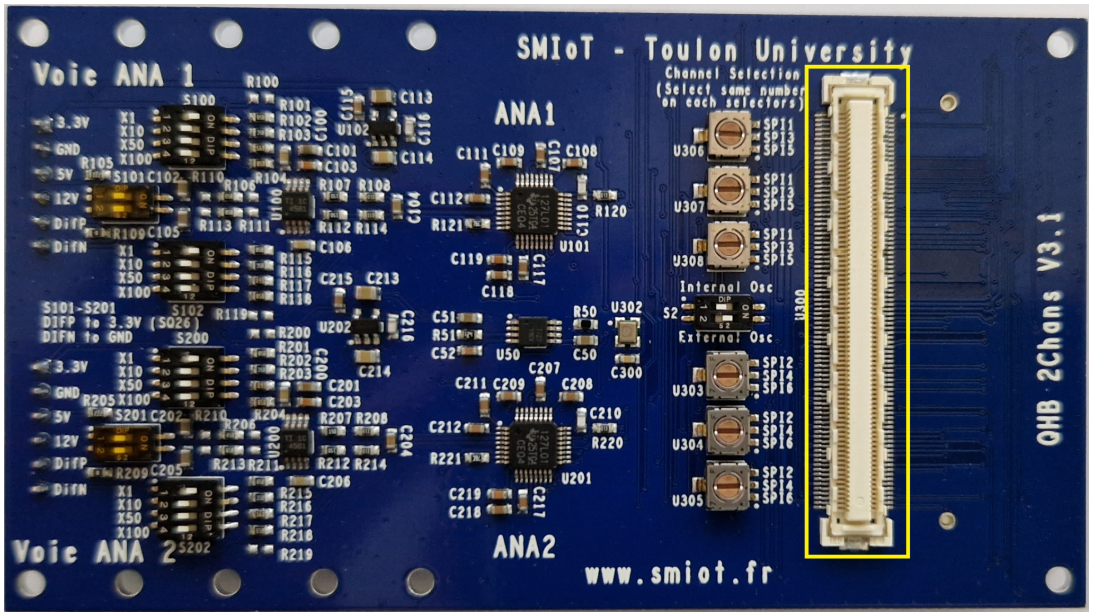
The USB Device Connector (USB type B) allows the user to use QHB as a peripheral device from a personal computer.

In this mode, the QHB operates as a device, and it is responsible to the host to grab data from the board.

On Daughter Board:

Extension Connector Top (U300)

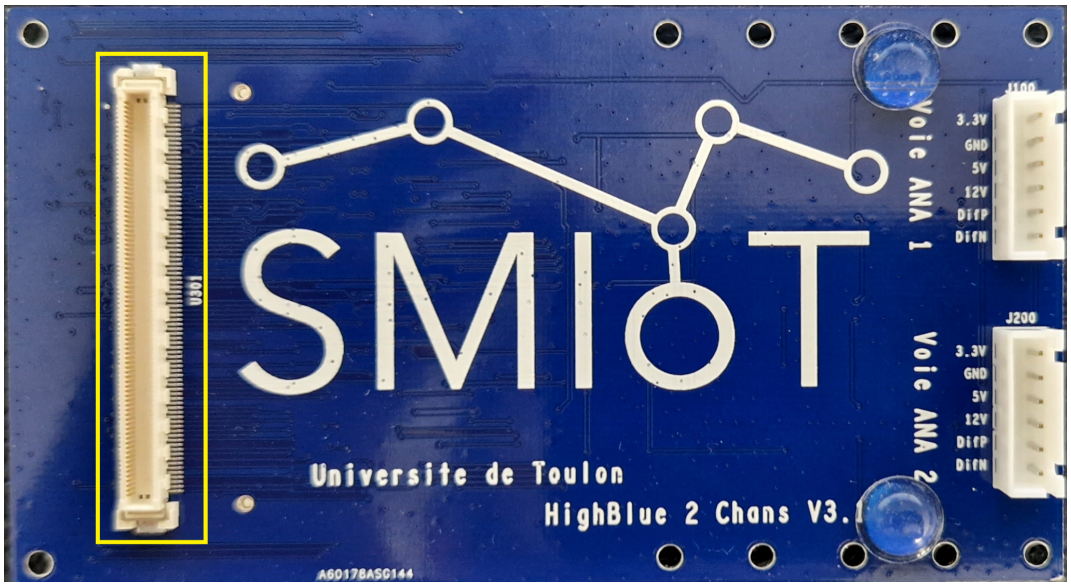
This connector is used to attach the Daughter board to the motherboard, or to another Daughter board (more than 2 channels)



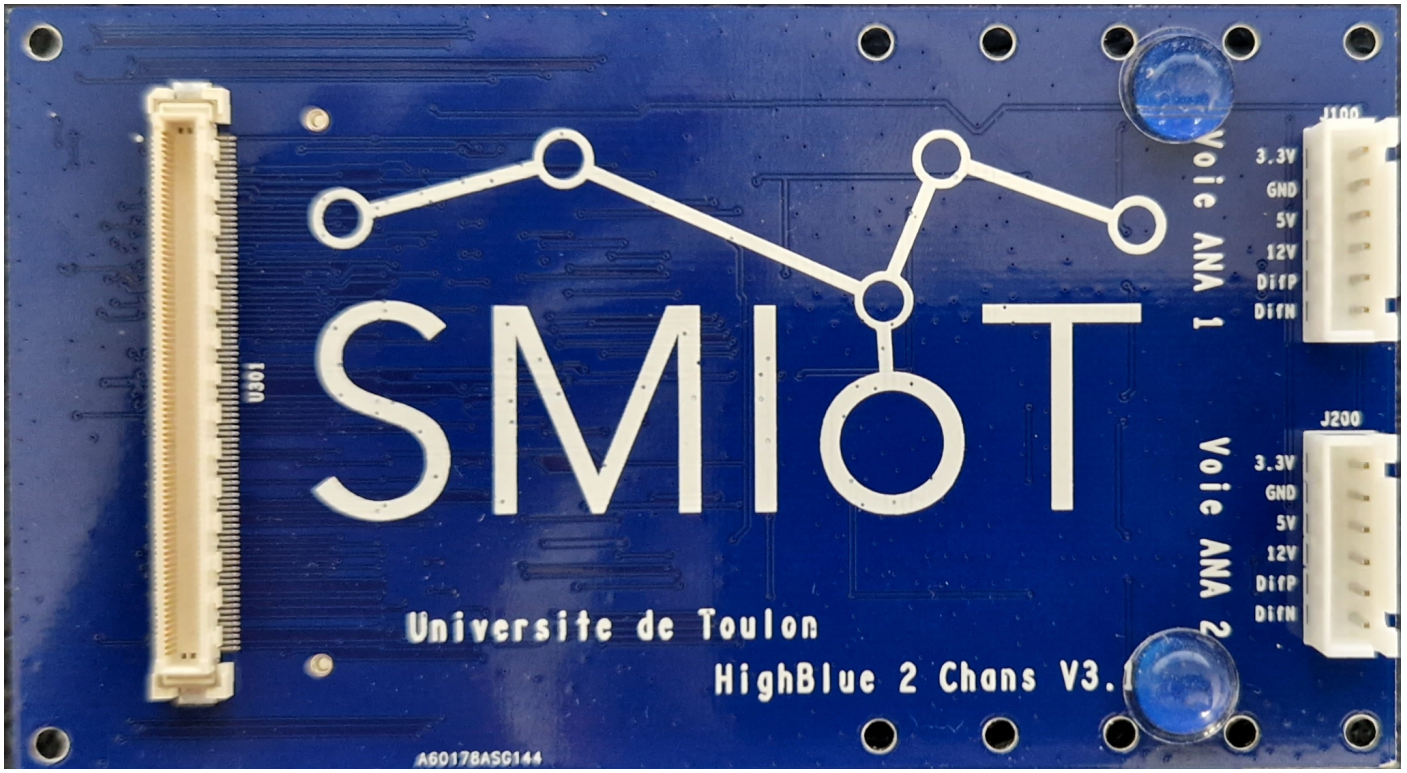
This is a 168 pin connector.

Extension Connector Bot (U301)

This connector is used to attach another Daughter Board to this Daughter board (more than 2 channels)



Hydrophone/Microphone/Line Input/Differential Input/DC Output (J100, J200)



When wiring hydrophones ensure work is accomplished in an anti-static environment, and be discharged of static load. (Avoid wool clothing and touch a point of grounding ie: PC casing, ...).

This connector is used to connect an Hydrophone, Microphone, or Line input to the acquisition board. It can also provide DC output to power hydrophone/microphone.

It use a JST connector: ***B6B-XH-A(LF)(SN)***

The cable to use have to be a JST: ***XHP-6***

PIN	FUNC
1	+3.3V Output
2	GND
3	+5V Output
4	+12V Output
5	DiffP (Positive Input)

6	DiffN (Negative Input)

In the case of a system in MONO configuration, the hydrophone is connected to the path "ANA1". In the case of a system configuration Stereo or more, the hydrophones are connected on both channels and/or on multiple daughter boards if more than 2 channels are used.

Hydrophone CXX:

<u>Connections to QHB:</u>

Hydrophone CXX from *Cetacean Research®* is a 3wire device (+VHydrophone, GND, Output signal). It accepts voltage input ranging from +5VDC to + 30VDC.

In case of a long wire between the board and the microphone (L>2 Meters), +12V output is preffered to power the hydrophone.

Otherwise +5V output is sufficient.

<u>Wiring of J100, J200:</u>

PIN	FUNC
1	N.C.
2	GND
3	+5V Hydrophone power (if short wire)
4	+12V Hydrophone power (if long wire)
5	DiffP Hydrophone signal
6	N.C.

For CXX, don't forget to configure the hardware input of the daughter boards.

HYDROPHONE SQ26:

Connections to QHB:

Hydrophone SQ26 from *Cetacean Research®* is a 2wire device (+VHydrophone/Output Signal, GND). It accepts voltage input ranging from +3.3VDC to + 5VDC.

Wiring of J100, J200:

PIN	FUNC
1	N.C.
2	GND
3	N.C.
4	N.C.
5	DiffP: Hydrophone signal + power on signal
6	N.C.

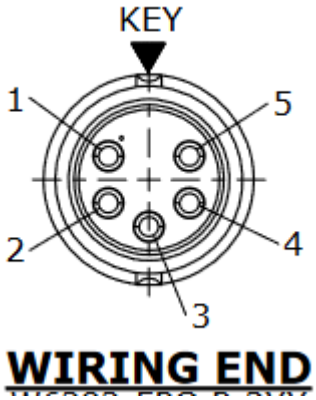
For SQ26, don't forget to configure the hardware input of the daughter boards.

MICROPHONE USMIOT:

Connections to QHB:

Microphone uSMIOT from *SMIoT®* is a 4wire device (+VCC,GND, OUT+, OUT-). It accepts voltage input ranging from +3.3VDC to + 5VDC.

Wiring End (**On microphone cable [Front view]**):



PIN	FUNC
1	GND
2	DIFFP
3	N.C
4	DIFFN
5	+5V

Wiring of J100, J200 (**On QHB Daughter Board**):;

PIN	FUNC	Microphone (Wire type1) Color	Microphone (Wire type2) Color
1	N.C.	N.C	N.C
2	GND	Yellow	No Color
3	VCC (+5V)	Red	Red
4	N.C.	N.C	N.C
5	DiffP: Microphone positive signal	White	Transparent
6	DiffN: Microphone positive signal	Blue	Blue

For Microphone, don't forget to configure the hardware input of the daughter boards.

SPECIFICATIONS

ABSOLUTE MAXIMUM RATINGS

		MIN	MAX	Unit
Voltage	VDD to GND without 12V output supply	4	40	V
	DIFFP to DIFFN	0	2.5	V
	Digital input	DGND-0.3	DVDD+0.3	V
	BACKUP Battery (CR2032)	1.3	3.6	V
Current	Input, continuous, any pin except power supply pins	-10	10	mA
	Timekeeping (From VBAT), VCC=0V	850	2300	nA
Température	Operating ambient, Ta	-40	100	°C

ESD RATINGS

		Value	**Unit**
V(ESD) Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101	±1000	

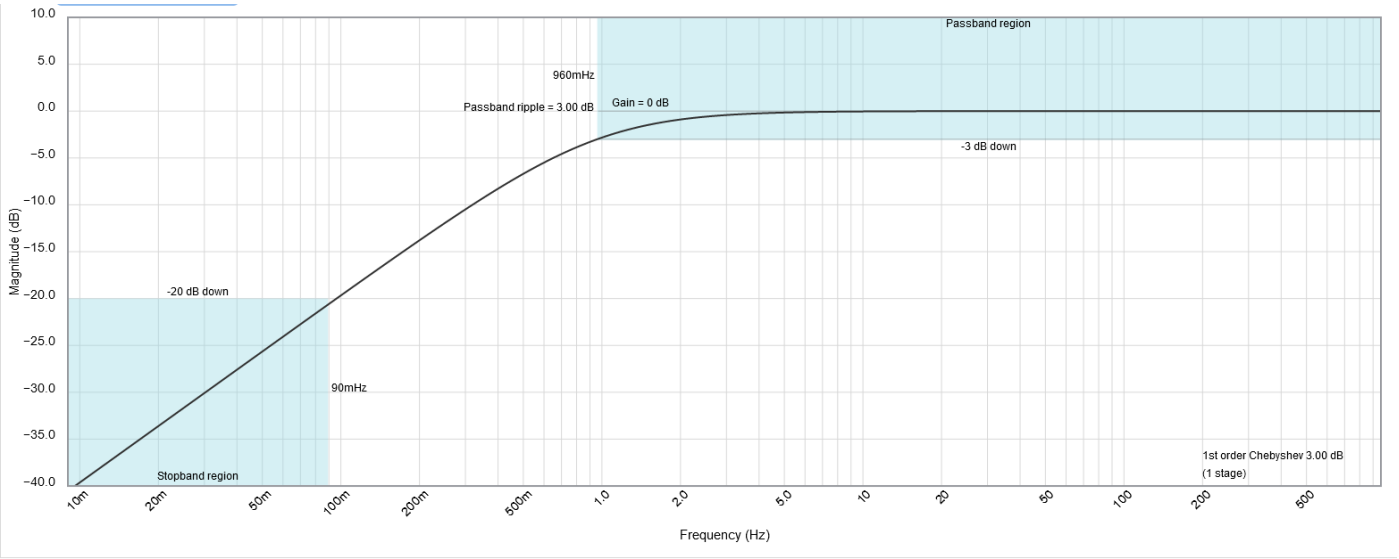
Electrical Characteristics

Minimum and maximum specifications apply from TA = –40°C to +100°C. Typical specifications are at TA = 25°C.

Characteristics of input filter

QHB Daughter board comes with a High-pass input filter.

It is a first order (C-R) High-Pass filter with a Cutoff frequency of 0.96Hz. It can be customised upon demand.



ADC Characteristics:

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	Unit
ANALOG INPUTS					
Differential input impedance	HR mode,				
DC PERFORMANCE					
Resolution	No missing codes	8	16	24	bits
DataRate	Wideband filters	512,256,128,64			KSPS
	Low-latency filters	512,128,32,8			

Integral nonlinearity	VCM=AVDD/2		2.5	10	ppm
offset error			±0.1		mV
Offset drift			1.5	3.0	µV/°C
Noise	WB2, OSR 32		10.6		µVRMS
	WB2, OSR 64		7.3	10.1	
	WB2, OSR 128		5.1	7.2	
	WB2, OSR 256		3.6	5.2	
CMRR	Common-mode rejection ratio fCM= 60Hz		95		dB
AC PERFORMANCE					
SNR	WB2, OSR 32		104.4		dB
	WB2, OSR 64	104.9	107.8		
	WB2, OSR 128	107.9	110.9		
	WB2, OSR 256	110.6	113.9		
THD	Total harmonic distortion		-113		dB

Characteristics of anti-aliasing Filter

Lowpass 1 (Wideband1): Cutoff frequency = 0.4 * Sampling Rate, constant gain in the passband, high attenuation beyond so as to avoid aliasing phenomena with an attenuation of 110 dB in the stopband.

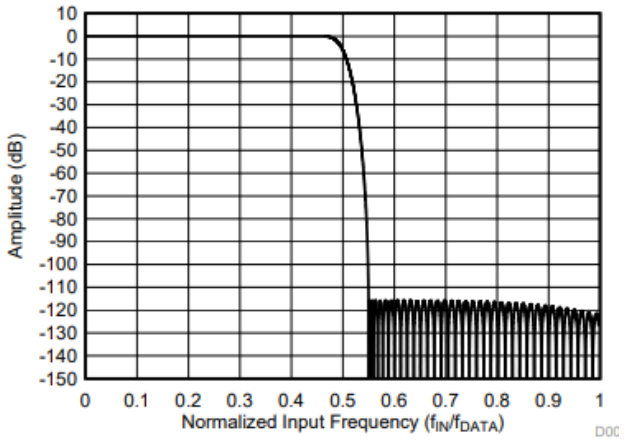


Figure 1: Transfer function of the filter WB1

Lowpass 2 (Wideband2): Cutoff frequency = 0.5 * SR. constant gain in the passband, high attenuation beyond so as to avoid aliasing phenomena.

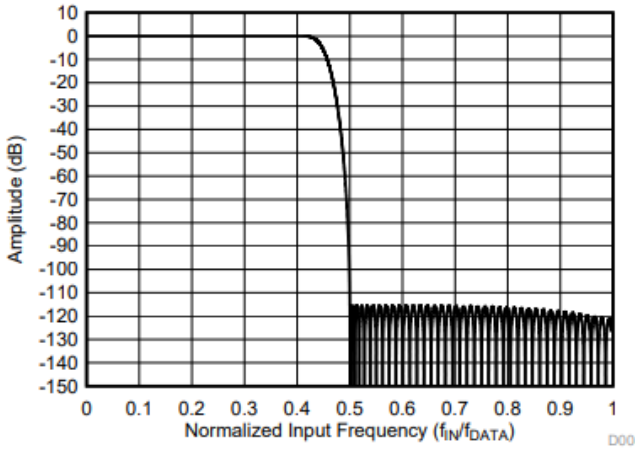


Figure 2: Transfer function of the filter WB2

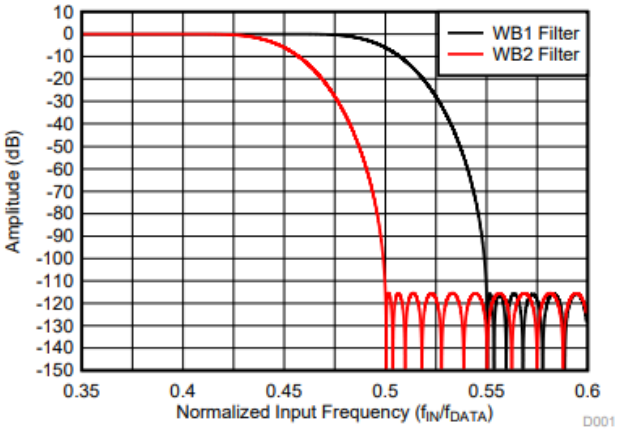


Figure 3: Comparison of transfer functions of filters WB1 and WB2

Filter Low Latency (sinc / sin5c): Constant phase shift between the output and input signals irrespective of the frequency of the input signal. In return, the gain is not perfectly consistent in bandwidth. The noise level is lower than with an anti-aliasing filter.

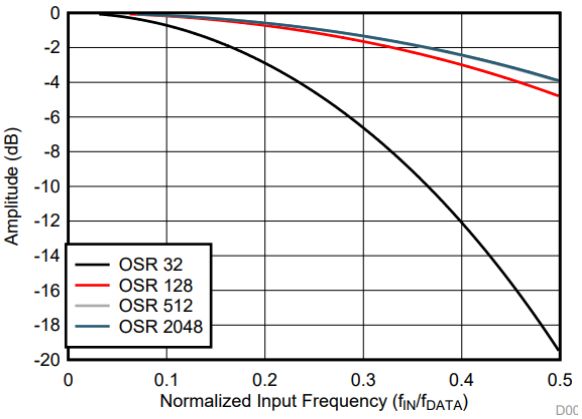


Figure 4: Filter Transfer Function Low Latency for frequencies below the Shannon limit

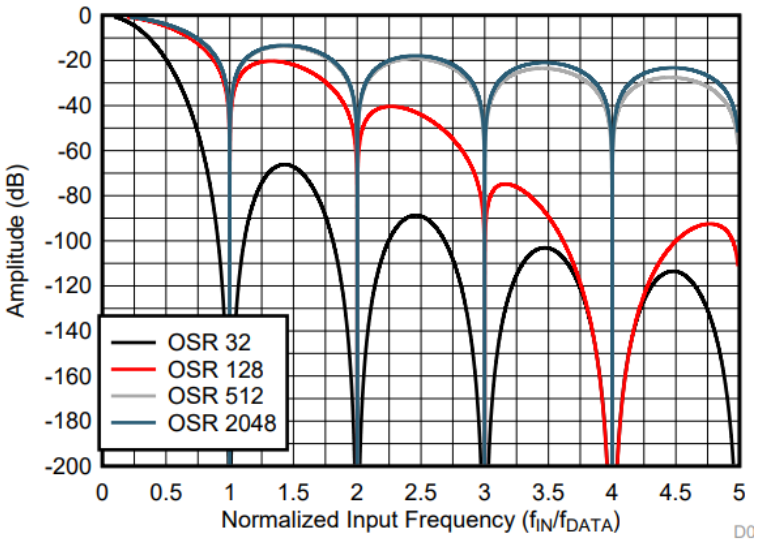


Figure 5: Filter Transfer Function Low Latency for a range of fréquencies beyond the Shannon limit frequency

FEATURES ANALOG DIGITAL CONVERSION STAGE:

Table 1. Wideband Filters Performance Summary at AVDD = 3.0 V, DVDD = 1.8 V, and 2.5-V Reference

MODE	DATA RATE (SPS)	OSR	TRANSITION BAND	PASS BAND (kHz)	SNR (dB)	V_{RMS_noise} (μV_{RMS})	ENOB	I_{DVDD} (mA)
High-resolution (HR)	512,000	32	Wideband 1 filter	230.4	103.7	11.61	18.72	7.50
			Wideband 2 filter	204.8	104.1	10.64	18.84	
	256,000	64	Wideband 1 filter	115.2	107.3	7.61	19.33	4.35
			Wideband 2 filter	102.4	107.7	7.25	19.40	
	128,000	128	Wideband 1 filter	57.6	110.4	5.35	19.83	2.80
			Wideband 2 filter	51.2	110.9	5.06	19.91	
	64,000	256	Wideband 1 filter	28.8	113.4	3.79	20.33	2.00
			Wideband 2 filter	25.6	113.9	3.58	20.41	

Figure 6: acquisition noise level depending on the configuration of wideband filters

Table 2. Low-Latency Filter Performance Summary at AVDD = 3.0 V, DVDD = 1.8 V, and 2.5-V Reference

MODE	DATA RATE (SPS)	OSR	-3-dB BANDWIDTH (kHz)	SNR (dB)	V_{RMS_noise} (μV_{RMS})	ENOB	V_{PP_noise} (μV_{PP})	I_{DVDD} (mA)
High-resolution (HR)	512,000	32	101.8	107.6	7.40	19.37	64.67	1.60
	128,000	128	50.6	110.8	5.12	19.90	44.11	1.39
	32,000	512	13.7	116.2	2.74	20.80	24.14	1.33
	8,000	2048	3.5	122.0	1.41	21.76	11.32	1.32

Figure 7: Noise level of acquisition depending on the configuration of Low Latency filters

Power Consumption:

All measurements were made with VCC=20.0V. GAIN X100 on each analog channel.

The daughter cards are not all fitted in all cases.

Recording

USB Device Mode

	Power consumption Max(mA)					
	Chan Count	**Sample Rate (KSPS)**				
		512	256	128	64	32
Daughter 2&3 not mounted	**1**	125	121	120	118	118
	2	126	121.5	120	118	119
Daughter 3 not mounted	**3**	145	138	134	132	132
	4	146	139	135	133	133
Daughter 1,2 &3 mounted	**5**	170	158	151	148	148
	6	171	159	152	148	148

USB Host Mode (USB HDD [Toshiba 1To])

The following measures include Hard drive consumption. (Model: Toshiba DTB310)

Power consumption Max(mA)						
	Chan Count	**Sample Rate (KSPS)**				
		512	256	128	64	32
Daughter 2&3 not mounted	**1**	228	215	206	210	224
	2	230	221	213	210	223
Daughter 3 not mounted	**3**	242	238	230	224	242
	4	242	236	233	225	242.5

Daughter 1,2 &3 mounted	**5**	275	251	244	237	262
	6	275	252	246	240	263

Sleep Mode

Power consumption in sleep mode includes RTCC Timekeeping.

Power consumption Max(mA)	
With RTCC Timekeeping	**5.84**

MANUAL

RECOMMENDATIONS OF USE

SAFETY PRECAUTIONS

In this manual, the warning signs and caution should be read by users to avoid dangerous accidents and problems. The meaning of these symbols is as follows:

If users ignore this symbol and mishandle the device, it can result in personal injury and damage to equipment.

Please read the safety tips and the following precautions to ensure a safe use of the JASON system.

FOOD: The power consumption of this device is low. It should only be operated by being powered by a type of continuous supply of 5 to 40V (or Li Ion / Batteries / battery according to the application, contact us).

- Lead acid batteries must be recharged using a 12V battery charger.
- When you disconnect the battery to perform charging, grasp the connector on the electronic board and never pull on the cable.
- Use a conventional 12V lead acid battery without changing the power cables.
- The QHB system can not be used to recharge the batteries.
- In case of no use, remove the batteries from the system.

ENVIRONMENT

To avoid problems and malfunctions, avoid using the system in an environment where it will be exposed to:

- Extreme temperatures (<-15 ° C;> 60 ° C)
- Heat sources such as radiators or stoves
- Excessive vibration or shock

HANDLING

- Do not place any objects filled with liquids, such as vases, on the open, as this may cause electric shock.
- Never place naked flame sources, such as lighted candles on the system as this may cause a fire.
- The QHB system is a precision instrument. Be careful not to drop or subject it to shock or excessive pressure, as this could cause serious problems.
- Make sure that no foreign objects (coins or pins etc.) or liquid (water, soft drinks and fruit juices) penetrate the unit.

Connecting cables and input / output

You should always turn off the system and all other equipment before connecting or disconnecting cables. Be sure to disconnect all connection cables and turn off the power before moving the system.

Modifications

Never attempt to modify it in any way. It may cause damage and be dangerous for the user.

PRECAUTIONS

ELECTRICAL INTERFERENCE

For security reasons, the system QHB was designed to provide maximum protection against the electromagnetic radiation from the device and to protect against external interference. However, any equipment that is very sensitive to electronic interference or that emits strong electromagnetic waves must not be placed near the system because the possibility of interference can not be completely eliminated. With any type of digital control device, including the QHB, electromagnetic interference can cause malfunctioning and corrupt or destroy data. Care must be taken to minimize the risk of damage.

CLEANING

Use a dry, soft cloth to clean the system. If necessary, dampen the cloth slightly. Do not use abrasive cleaners, waxes or solvents (such as paint thinner or cleaning alcohol), since these materials may dull the finish, damage the surface or cause damage to the PCB.

Please keep this manual in a safe place for future reference.

INSTALLATION

UNPACKING:

As with any electronic device, you should take care to handle this equipment carefully. Before removing the device from its packaging, discharge yourself of any static charge using a wrist strap or by simply touching the computer chassis or other grounded object to eliminate any stored static charge. Contact us immediately if any components are missing or damaged.

INSTALLING THE HARDWARE:

The hardware of the system should be delivered already assembled. No additional installation is required, except in certain cases. Only the connection of the IO and power supply should be required.

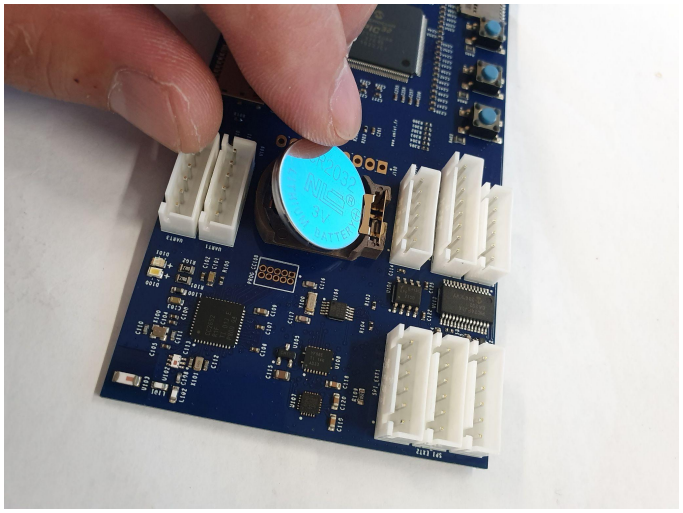
INSTALLING THE CR2032:

To install the CR2032 battery, please follow the steps below:

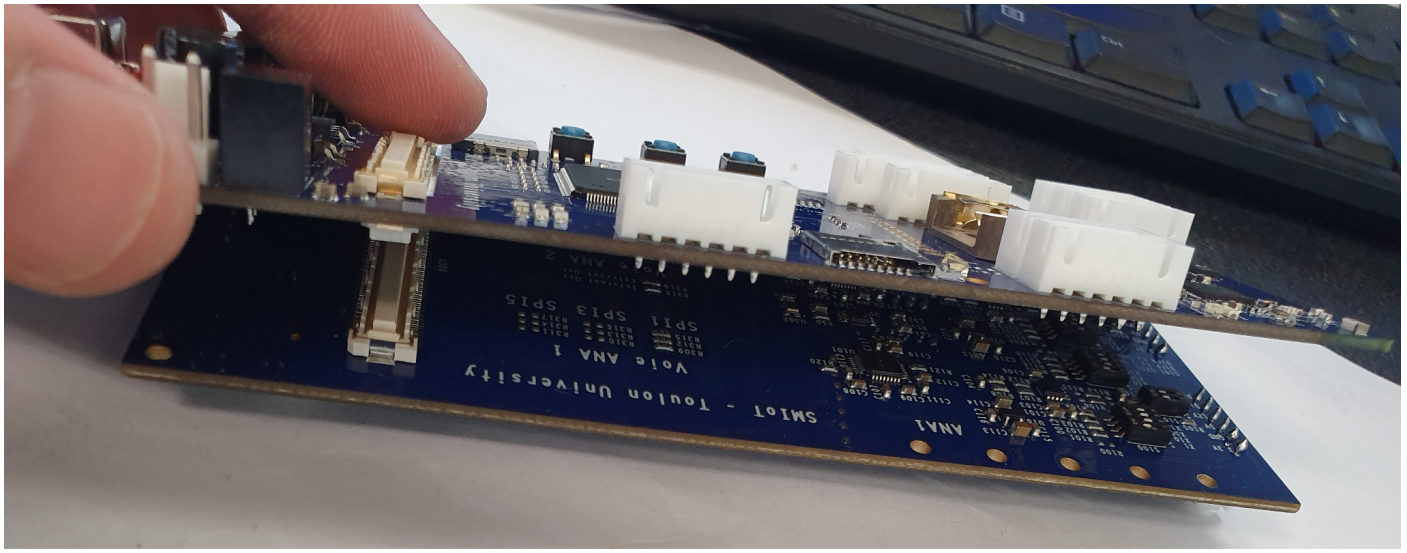
1. Turn ON Power on board
2. Update the system time by software or configuration script
3. Place the coin battery
4. Turn off the power

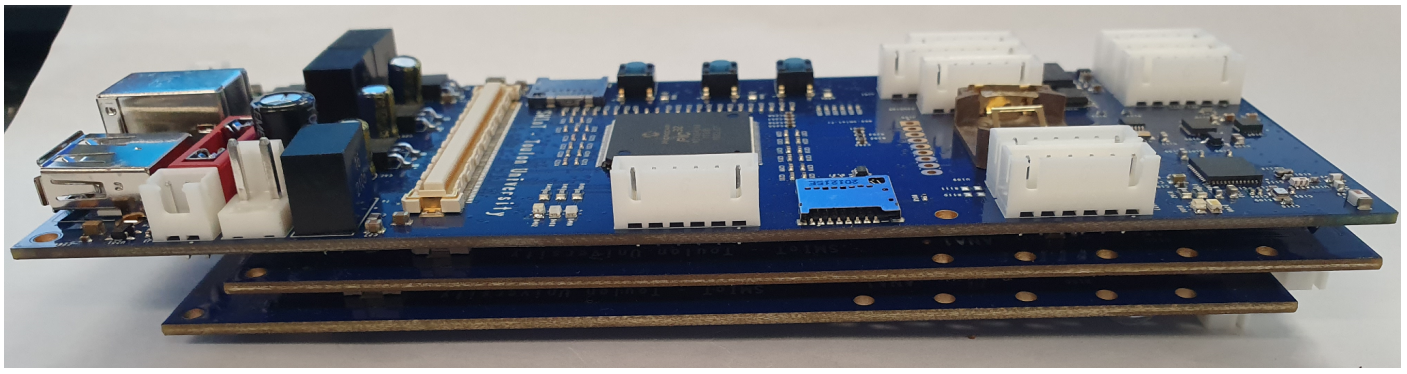
Note: The system has to be powered before placing the backup battery.

To place the coin battery on board, please insert it under the tongue then press it.



Stacking Multiple Daughter Boards:





System Startup:

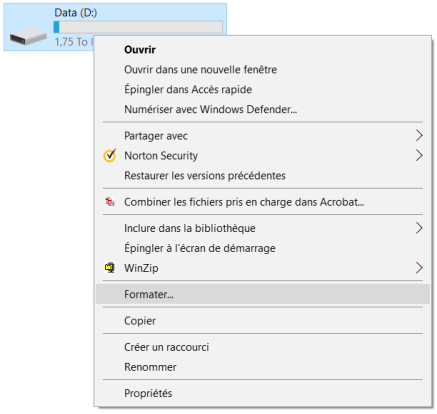
Commissioning is very simple. Please accomplish the following steps in order:

Formatting the storage medium

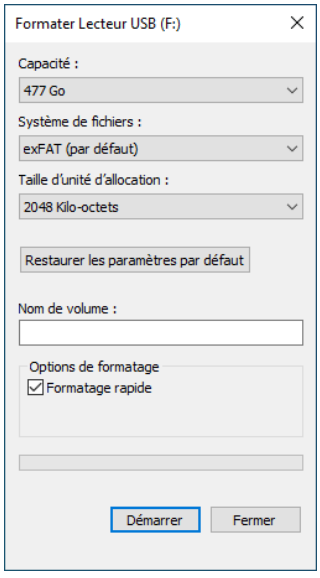
The QHB system takes into account the FAT / FAT32 /exFAT file systems.
It is therefore recommended to format the storage media to use **exFAT**.

Please preferably use fast storage media to benefit from a high transfer rate, and avoid packet loss (eg Western Digital Element 1TB).

Formatting can be done via the Windows format utility (right click on the media to format):



Go to the desktop of your system, right-click the storage media format -> "Format".



Select a unit of allocation of **2048ko**.

Click "Start".

Wait for the media to be formatted.

SOFTWARE CONFIGURATION:

The system parameter (and / or updates) via the text configuration file "JConfig.CFG" given below :

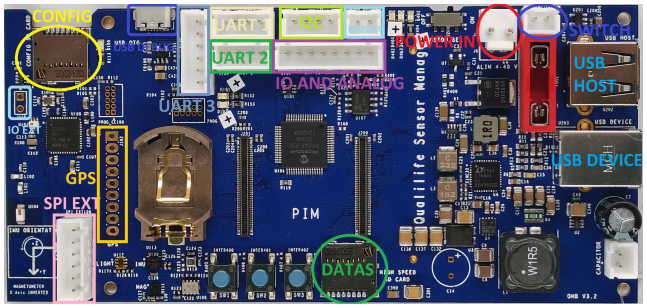
WARNING: This file is placed in the root path of config sdcard. Its content is "Case sensitive"

```
//System Configuration File for QHBV3
Sampling_Resolution=16;        // 16 = Resolution in bits (8, 16 or 24)
Sampling_Freq=128000;          // 256000 = Sampling frequency(in sample per sec)
                               //Possibles values are 512000,256000, 128000,64000 With WidBand
                               // Filters,
                               //or 512000,128000,32000,8000 With Low Latency filter
Filter_Selection=1;            //filter selection. Possibles values are:
                               //0->Wideband 1 (0.45 to0.55)×fDATA
                               //1->Wideband2 (0.40 to0.50)×fDATA
                               //2->LowLatency
AutoStart=true;                //true = Auto record at boot
WakeUpOnMAG=true;              //WakeUp board/Start/Stop on MAG Threshold
FILE_Size_Limit=200;           //File Size limitation (in Mbytes)
Record_Use_TimeInterval=true;    //Set or unset the discrete recording
Shutdown_Duration=755;         //Time period of wait time between each record (in seconds)
Preparing_Duration=5;          //Time to boot and prepare Pic 32 (SD Card or HDD is not the same)
Recording_Duration=120;        //Time period of record (in seconds)
Stopping_Duration=20;          //Time to stop Pic 32 (SD Card or HDD is not the same)
Channel_Count=5;               //Number of channels to record
Storage_Target=SD;             //Storage target ("SD" for SD card and hard disk drive or "USB"
                                      //for Device mode [PC Connected])
Disable_LEDs=true;             //Disable Leds after 30 sec (only in autonomous mode)
BatteryVoltageLimit=4;         //Battery Voltage Limit (in volts) to put system OFF an preserve
                               //battery
SaveSensorDataInConfigCard=true;//Allow sensors data to be saved in Config Card
FilePrefix="";                        //Put a prefix on filenames (max 32 char without spaces)

//Sensors Configuration
//LIGHT
LightSensorGain=LOW;           //LOW(x1), MED(x25), HIGH(x428), MAX(x9876)
LightSensorIntegrationTime=100;    //Possibles values are 100, 200, 300, 400, 500, 600 (in ms)
//PRESSURE
PressureSensorFreq=50;         //Possibles values are 200, 100, 50, 25, 12.5, 6.25, 3.1, 1.5, 0.78,
                               //0.39, 0.2, 0.1, 0.05, 0.02, 0.01 (in Hz)
//MAGNETOMETER
MagnetometerFreq=10;           //Possibles values are 0.625, 1.25, 2.5, 5, 10, 20, 40, 80, 155, 300,
                               //560, 1000 (in Hz)
MagnetometerFullScale=4;    //Possibles values are 4, 8, 12, 16 (in Gauss)
//IMU
AccelerometerRange=2;          //Possibles values are 2, 4, 8, 16 (in G)
AccelerometerFreq=100;         //Possibles values are 1.5625, 3.125, 6.25, 12.5, 25, 50, 100, 200,
                               //500, 1000, 2000, 4000, 8000 (in Hz)
GyroscopeFullScale=2000;    //Possibles values are 15.625, 31.25, 62.5, 125, 250, 500, 1000, 2000
                               //(in Degrees per sec)
GyroscopeFreq=100;     //Possibles values are 12.5, 25, 50, 100, 200, 500, 1000, 2000,
                               // 4000, 8000 (in Hz)
//GPS
UseGPS=true;                   //Indicate that a GPS is present on system. Log GPS data at 1Hz
                               // Rate
```

```
SynchronizeBoardTimeGPS=true;//Allow system to Update system time with GPS time


//Optionnal (Debug)
DEBUG=DEBUG_ALL;                //Permet de logger les etats du system. (DEBUG_ALL permet de logger sur
                                //la console, sur l'UART, et dans un fichier.log de la carte SD de
                                //config)
                                //Possibles values are: NONE, DEBUG_ALL, DEBUG_UART,
                                //DEBUG_FILE, DEBUG_CONSOLE
```

If this file is not present, the recordings will not start.

This file has to be placed in the "**Config**" µSD card slot.



Software parameters Description

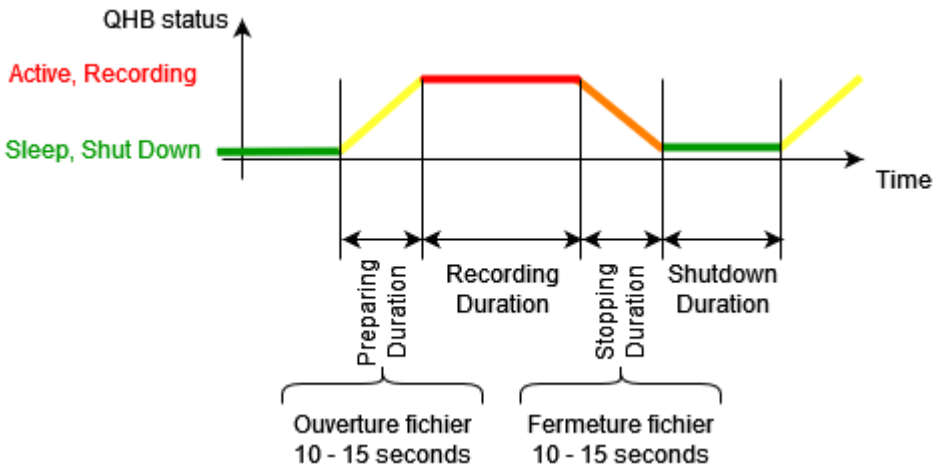
The following tab describes the customizable parameters of QHB.

<table>
<tr><th>Parameter Name</th><th>Description</th></tr>
<tr><td>Sampling_Resolution</td><td>this configures the sampling resolution in bits.
<table><tr><th>Possibles values are:</th></tr><tr><td>24</td></tr><tr><td>16</td></tr><tr><td>8</td></tr></table></td></tr>
<tr><td>Sampling_Freq</td><td>This is the sampling frequency in Sample per second.
Possibles values are:
<table><tr><th>With Wideband filter</th><th>With Low Latency Filter</th></tr><tr><td>512000</td><td>512000</td></tr><tr><td>256000</td><td>128000</td></tr><tr><td>128000</td><td>32000</td></tr><tr><td>64000</td><td>8000</td></tr></table></td></tr>
<tr><td>Filter_Selection</td><td>This sets the anti aliasing filter.
Possibles values are:
<table><tr><th>Value</th><th>Description</th></tr><tr><td>0</td><td>Wideband1 (0.45 to 0.55 x fDATA)</td></tr><tr><td>1</td><td>Wideband2 (0.40 to 0.50 x fDATA)</td></tr><tr><td>2</td><td>LowLatency</td></tr></table></td></tr>
<tr><td>AutoStart</td><td>This parameter allow the system to start recording</td></tr>
</table>

<table>
<tr><td></td><td>automatically upon power on.<table><tr><th>Value</th><th>Description</th></tr><tr><td>true</td><td>Record will automatically start at boot</td></tr><tr><td>false</td><td>Record will not start automatically</td></tr></table></td></tr>
<tr><td>FILE_Size_Limit</td><td>This indicates the maximum file size in bytes. (file will be splitted)</td></tr>
<tr><td>Record_Use_TimeInterval</td><td>This set or not the discrete recording mode.<table><tr><th>Value</th><th>Description</th></tr><tr><td>true</td><td>Enable discrete recording</td></tr><tr><td>false</td><td>Continuous recording</td></tr></table></td></tr>
<tr><td>Shutdown_Duration</td><td>This set the time of sleep period (in seconds)</td></tr>
<tr><td>Preparing_Duration</td><td>Time to boot and to prepare filesystem (in seconds)</td></tr>
<tr><td>Recording_Duration</td><td>Time of the record period (in seconds)</td></tr>
<tr><td>Stopping_Duration</td><td>This set the time to let the system to flush DDR and close file (in seconds)</td></tr>
<tr><td>Channel_Count</td><td>This set the number of Channels to acquire.</td></tr>
<tr><td>Storage_Target</td><td><table><tr><th>Value</th><th>Description</th></tr><tr><td>SD</td><td>This sets the system to save data on USB Flash drive or Data SD Card. (standalone Mode)</td></tr><tr><td>USB</td><td>This sets the system to use Device Mode. (Peripheral Mode)</td></tr></table></td></tr>
</table>

Operation Sequence in Standalone Mode

The graph below indicates how the system operates in “standalone” and “Discrete recording” mode.



Updating the date and time of the system:

The system set or updates board current Time via a text configuration file "CLOCK.CFG" in the following form:

```
CLOCKTIME= 11/02/2018 10:02:00;
```

To update the system, the CLOCK.CFG file must be placed in the Config folder. Then insert the mass storage in QHB, and turn-ON the system.

The system will read the content of the CLOCK.CFG, update Time, then delete it. The date and time are kept current as the battery backup (CR2032) is present on the system.

Hardware Configuration:

On the Daughter boards, there are some Dip Switches that should be configured depending on usage.

Daughter Board Input Configuration (S101, S201)

There are Two configuration DIP Switch (S101, S201) on the board.

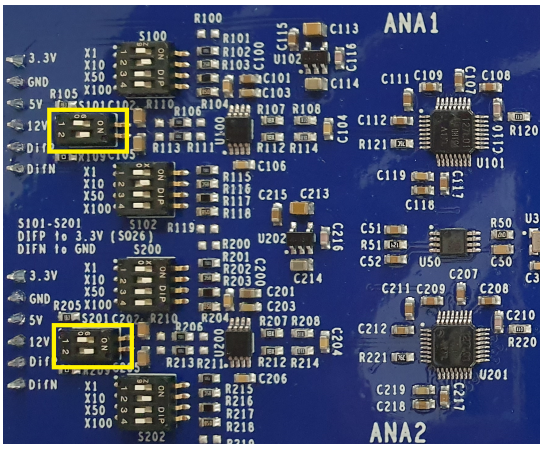
Switch number	"ON"	"Off"
1	Superposing 3.3V on Signal (SQ26)	Others
2	Connect DiffN to GND (Single Ended Input)	Differential Input

Example of Configuration Of Daughter Board Input For **Cxx** Hydrophones (S101, S201)

When using a **CXX** Hydrophone, the daughter board have to be configured for single input without superposing VCC on Signal like follow:

Switch number	State
1	**"Off"**
2	**"ON"**

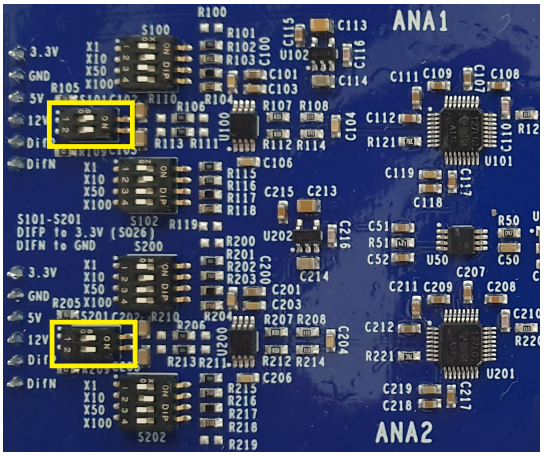
This configuration also work for Line Input.



Example of Configuration Of Daughter Board Input For **SQ26** Hydrophones (S101, S201)

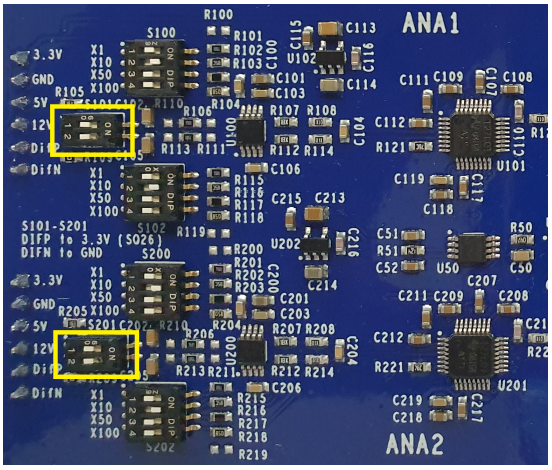
When using a **SQ26** Hydrophone, the daughter board have to be configured for single input without superposing VCC on Signal like follow:

Switch number	State
1	**"ON"**
2	**"ON"**



When using a differential input, the daughter board have to be configured for differential input without superposing VCC on Signal like follow:

Switch number	State
1	**"Off"**
2	**"Off"**



Daughter Board Digital Output Routing Selection

This is the only one hardware modification that is possible to do according to the use case.

This applies when the number of channels needed is more than 2.

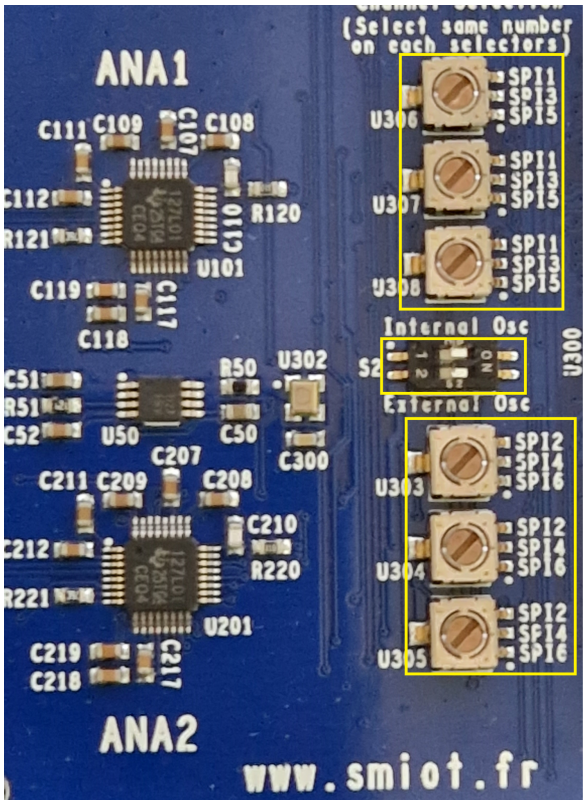
As the daughter cards are all identical, it is necessary to assign them a digital channel. To do this, a small hardware modification may be necessary.

Indeed, on the boards, switching resistances are present for this purpose. They allow you to route an output channel to a specific input on the motherboard.

The Routing of the channels have to be ordered.

One or Two Channels Configuration example:

For example, if only one or two channels are needed, these channels have to be routed to SPI1 and SPI2, and **must use internal OSC**.



This indicate that ANA1 is routed to SPI1

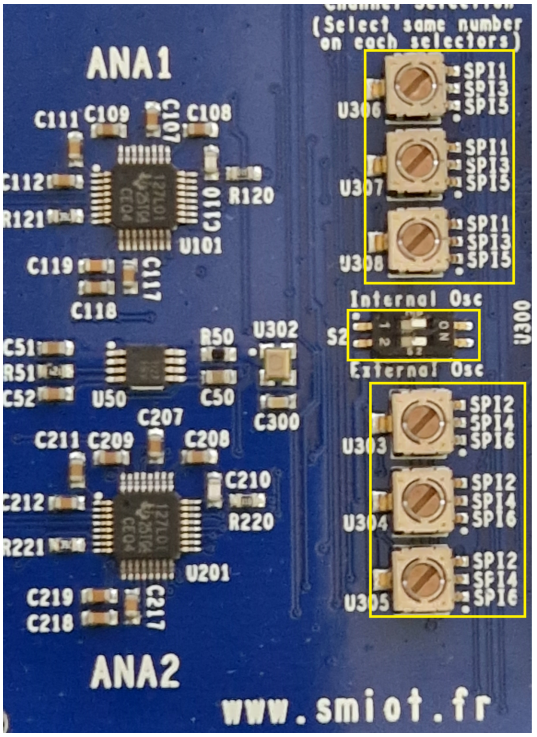
This indicates that the ADC uses it's internal OSC.
This indicate that the OSC of this board is routed to other boards (if present)

This indicate that ANA2 is routed to SPI2

Four Channels Configuration exemple:

For example, if four channels are needed, these channels have to be routed to SPI1 and SPI2, SPI3 and SPI4, First Daughter board have to use internal OSC and have to provide OSC for other Daughter boards.

For the first Daughter Board:

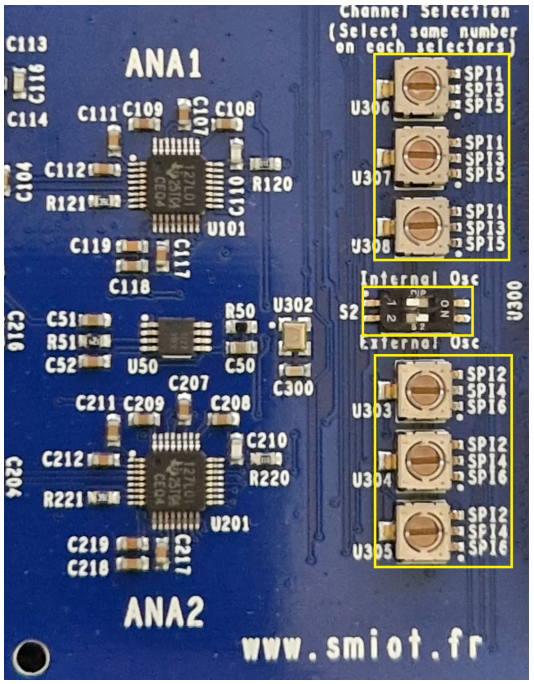


This indicate that ANA1 is routed to SPI1

This indicates that the ADC uses it's internal OSC. This indicate that the OSC of this board is routed to other boards (if present)

This indicate that ANA2 is routed to SPI2

For the second Daughter Board:



This indicate that ANA1 (of the second board) is routed to SPI3

This indicates that the ADCs use the OSC provided by other Daughter Board.

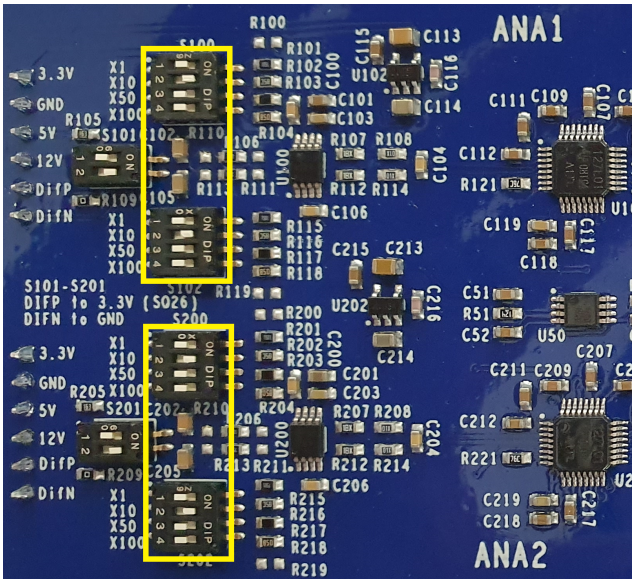
This indicate that ANA2 (of the second board) is routed to SPI4

Daughter Board Analog Gain Configuration (S100-S102, S200-S202)

There are Four configuration DIP switches (S100-S102, S200-S202) on the board. They allow users to customize input Gain.

The switches are working by pair. So S100 and S102, S200 and S202 MUST Have the same value.

Switch number				Gain Value
1	**2**	**3**	**4**	A (dB)
0	0	0	0	Do Not Use
1	0	0	0	X1 (1dB)
0	**1**	0	0	X10 (20dB)
0	0	**1**	0	X50 (34dB)
0	0	0	**1**	X100 (40dB)
1	**1**	0	0	X0.9(-0.91dB)
1	**1**	**1**	0	X0.89 (-1dB)
1	**1**	**1**	**1**	X0.89 (-1dB)
0	**1**	**1**	0	X8.32 (18dB)
0	**1**	**1**	**1**	X7.68 (17dB)
0	0	**1**	**1**	X33.27 (30dB)
Others				Do Not Use



System Startup

If "Autostart" = true, then the system will start the recordings with the parameters of the configuration file from its power.

Orange LED located on the capture card should light indicating that the system is recording.

Stop system and recovery measures

For powering down the tube under water, it is sufficient to rotate the cap on the top of tube tape counterclockwise (white arrow).

All LEDs on the card must go out. The measured data is saved continuously on the µSD storage system. These are directly saved as a .log file.

Note: During the shutdown, it is possible that the last record is lost. This is why it is necessary to ensure enough wait time after the start of a record (greater than or equal to the parameter "Record_time"), or else to have a "FILE_SIZE_LIMIT" reduced (which has the effect of cutting the recording file size).

To recover the data on the card µSD, refer to the next chapter "of the tube opening procedure".

.Log File Descriptor

File Structure Overview

The .log file is a binary file that contains audio datas, information about record (sampling frequency, resolution, …), as well as size of fields which made it up (Header size, DataBloc size,...).

Fichier .log
Header
Additionnal_DataBloc 1
DataBloc 1
Additionnal_DataBloc 2
DataBloc 2
. . .
Additionnal_DataBloc N
DataBloc N

Header Description

Header is the file structure descriptor. It contains information about records, and technical information about the .log file itself.

The Header contains the following fields (ordered):

Length (bytes)	Type	Nom	Description
4	ulong	headerSize	Size of header this field excluded.
2	ushort	versionNumber	Software revision Octet 1 | Octet 0 Major Rev | Minor Rev
1	uchar	numberOfChan	Channels count used during record
1	uchar	resolutionBits	Résolution of record (in bits)
4	ulong	samplingFrequency	Sampling Frequency (in Sample per sec)
4	ulong	dmaBlockSize	Size of DMA bloc. (Bloc that contains audio datas, grouped together in a sub-block for each of the channel)
4	ulong	sizeOfAdditionnalDataBuffer	Size of additionnal data bloc. (Datas IMU, GPS, others,...)
1	uchar	numberOfExternalPeripheral	Number of external peripheral (IMU, …)
4	ulong	timeStampOfStart	TimeStamp local (timeStamp du High Frequency Recorder) du debut d'enregistrement.
Variable	PERIPHERAL_CONFIGURATION[ ]	periphConfig[ ]	Tableau de structure de type PERIPHERAL_CONFIGURATION contenant la configuration de chacun des périphériques externes. Tableau de "numberOfExternalPeripheral" PERIPHERAL_CONFIGURATION

Additionnal_DataBloc Description

The Additional DataBloc contains datas coming from external sensors such as IMU, GPS, …
They are written in the same file as audio data (.log file) which allow synchronisation between various units. (Audio data, light data, absolute position, …)
The datas contained in this block are formatted like a simple frame defined by the UTLN protocol.
The size of this block is defined in the header of the file.
By default, the additional bloc size is **736** bytes, and can contain null values if no additional data are inserted in dataflow..

DataBloc Description

The DataBloc is the block that contains audio datas. They are of variable length (of the size indicated by the field “dmaBlockSize” of Header), In the current configuration, the default size is **65536** octets.
Those blocks are splitted by the number of channels.

DataBloc
Chan 1
Chan 2
...
Chan N

The audio length contained in one DataBloc it varies according to:

- Sampling Frequency
- Channels count
- Acquisition resolution

This length can be calculated by the following manner:

$$t = \frac{dmaBlockSize \div numberOfChan}{resolutionBits \div 8} \times \frac{1}{samplingFrequency}$$

Expression of number of DMABloc contained in a file:

$$nbBlock = \frac{(Record\ length \times samplingFrequency \times numberOfChan \times \frac{resolutionBits}{8})}{dmaBlockSize}$$

Expression of file size (in bytes) according to parameters:

$$Size = nbBlock \times (dmaBlockSize + sizeOfAdditionnalDataBuffer) + headerSize + 4$$

Noise Measurement

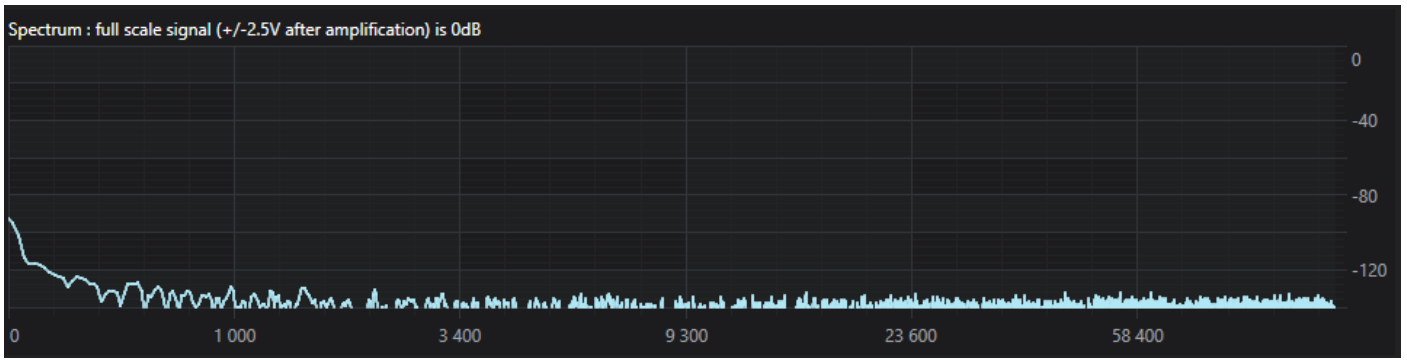
Measurement are done with VCC=20.0V, Fe=512000SPS, res=24 bits

Single Ended - Input Shorted to GND

In this part, maximum signal level (+/- 2.5V) corresponds to 0dB.

GAIN X1

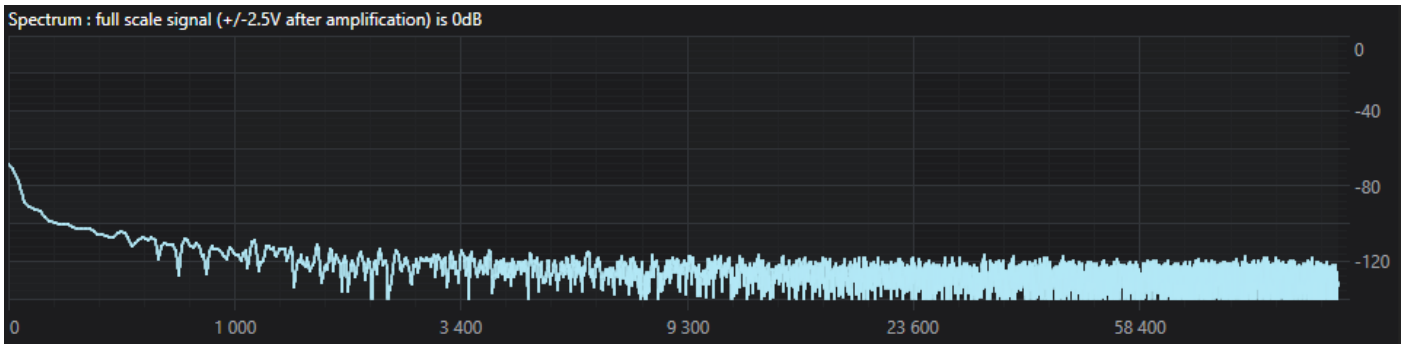
Noise spectrum in mel scale



Noise level with single input shorted to ground is below -126dB for frequencies higher than 1kHz, and below -120dB for frequencies up to 1kHz. This leads to 21 significant bits in x1 amplification mode.

GAIN X10

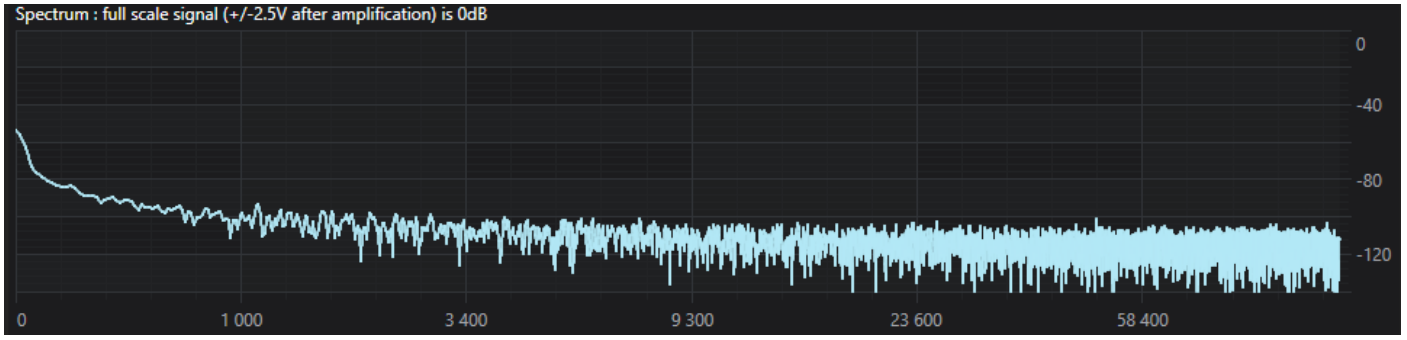
Noise spectrum in mel scale



Noise level with single input shorted to ground is below -106dB for frequencies higher than 1kHz. This leads to 18 significant bits in x10 amplification mode.

GAIN X50

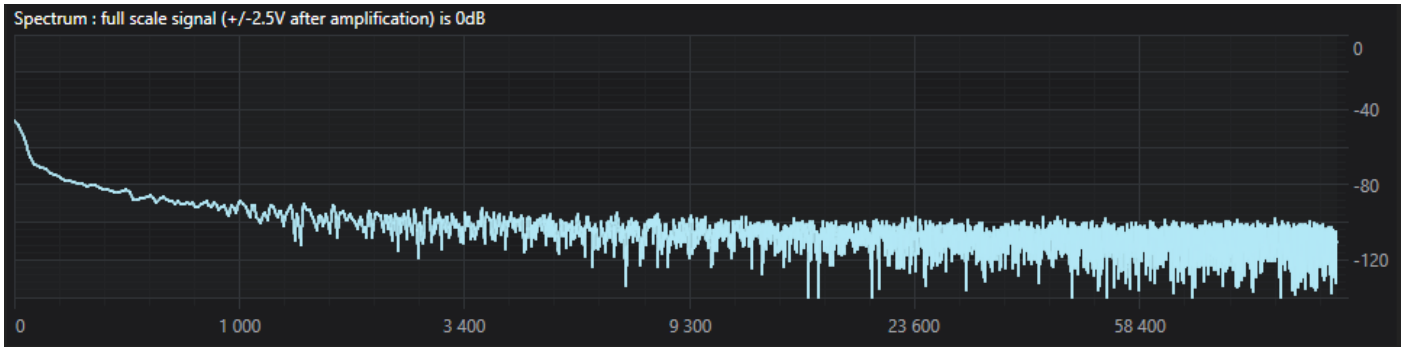
Noise spectrum in mel scale



Noise level with single input shorted to ground is below -92dB for frequencies higher than 1kHz. This leads to 16 significant bits in x50 amplification mode.

GAIN X100

Noise spectrum in mel scale



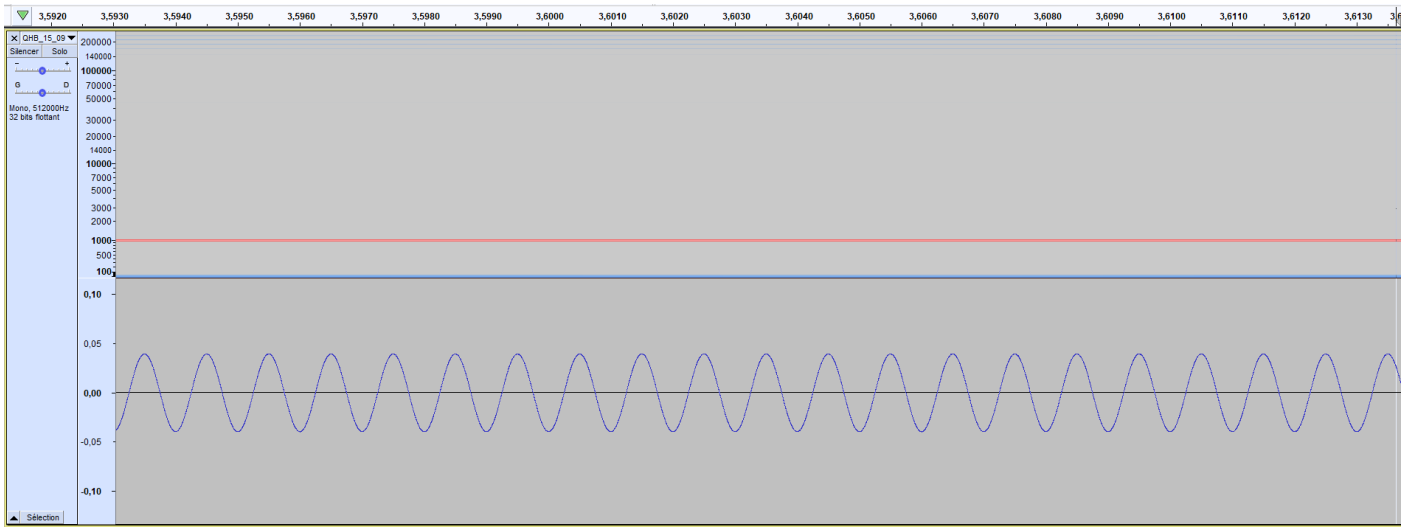
Noise level with single input shorted to ground is below -86dB for frequencies higher than 1kHz. This leads to 15 significant bits in x100 amplification mode.

Single Ended - Pure Sine Input

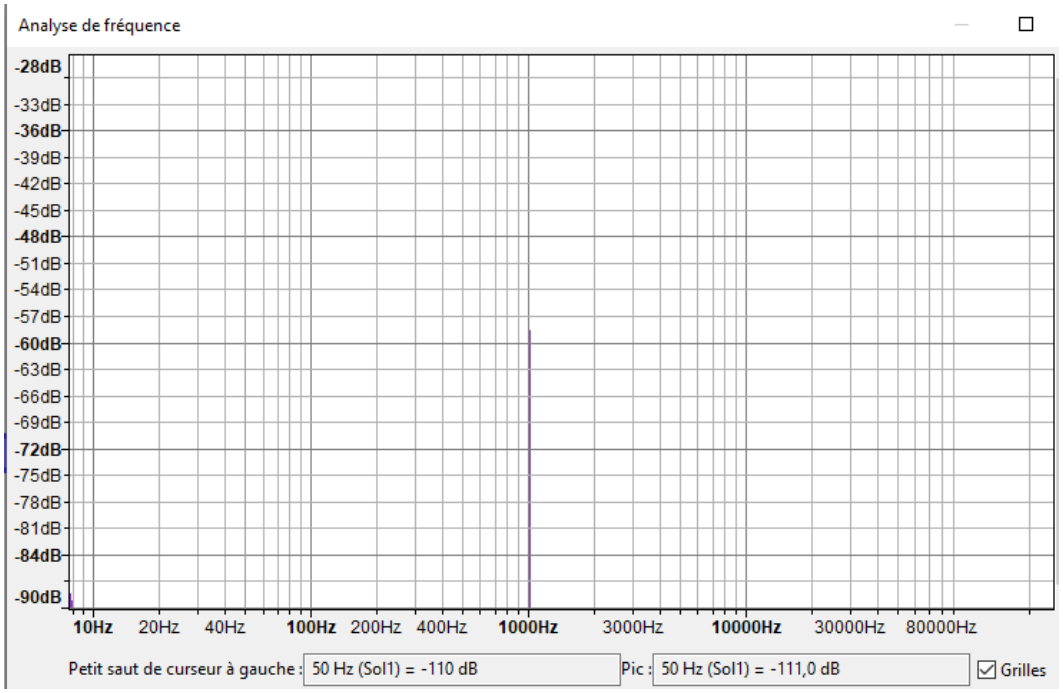
Pure sine 100mV F=1kHz

Gain X1

Waveform and spectrogram



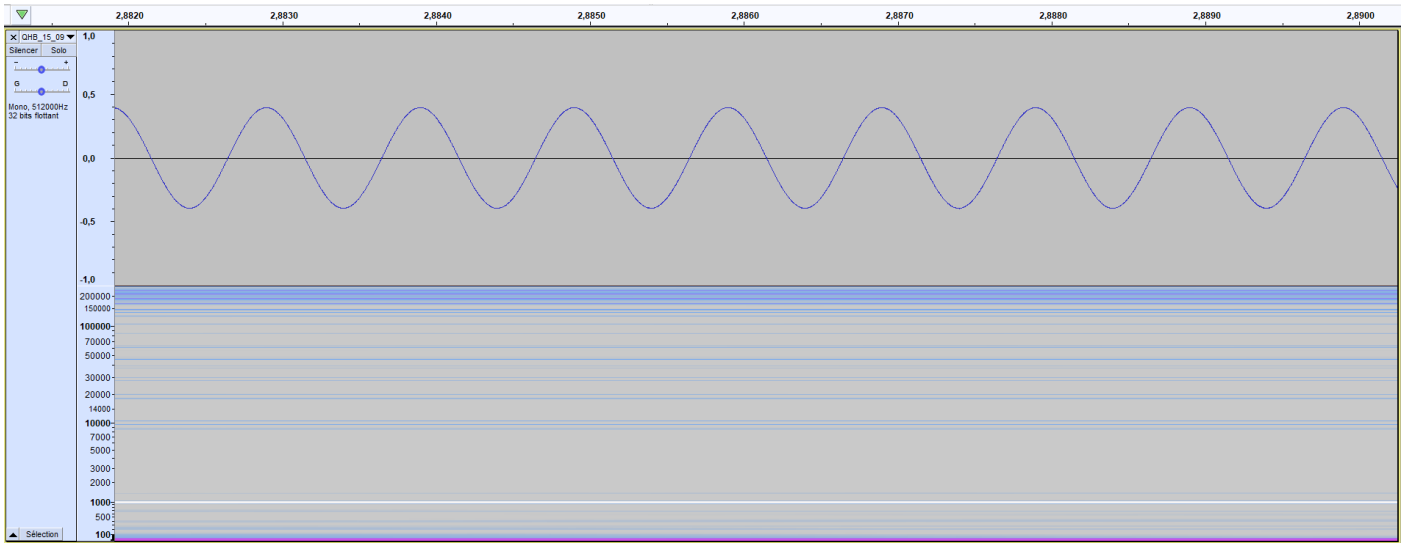
Spectrum



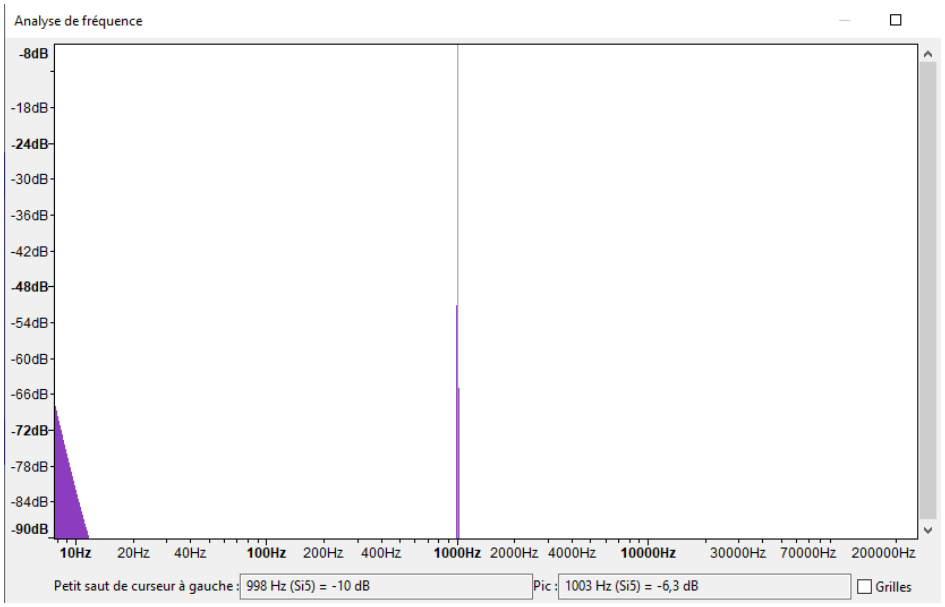
Noise level below **-110dB**

Gain X10

Waveform and spectrogram



Spectrum

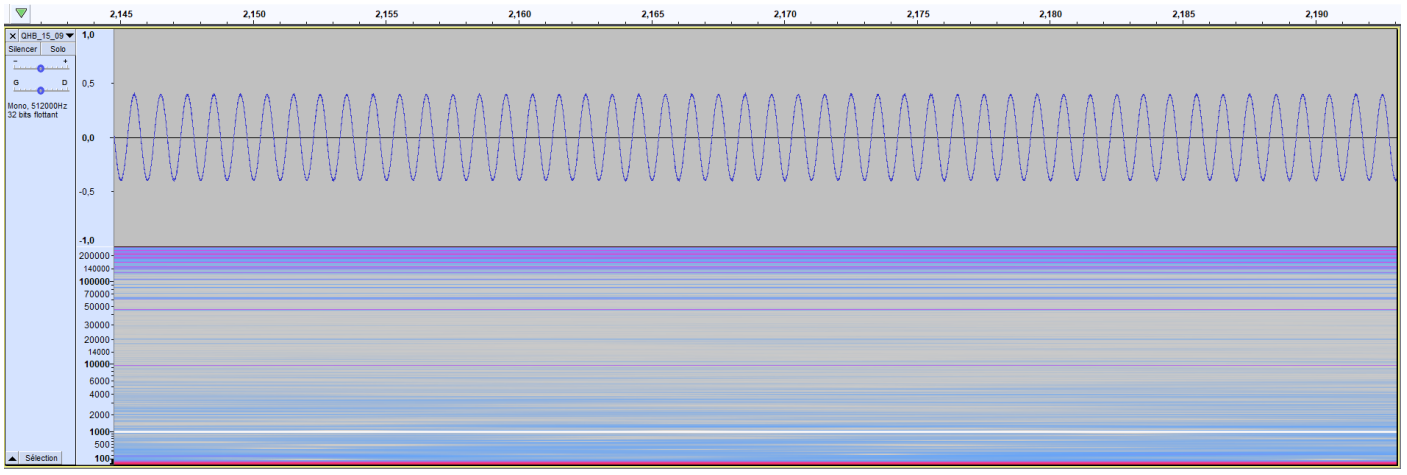


Noise level below **-110dB**

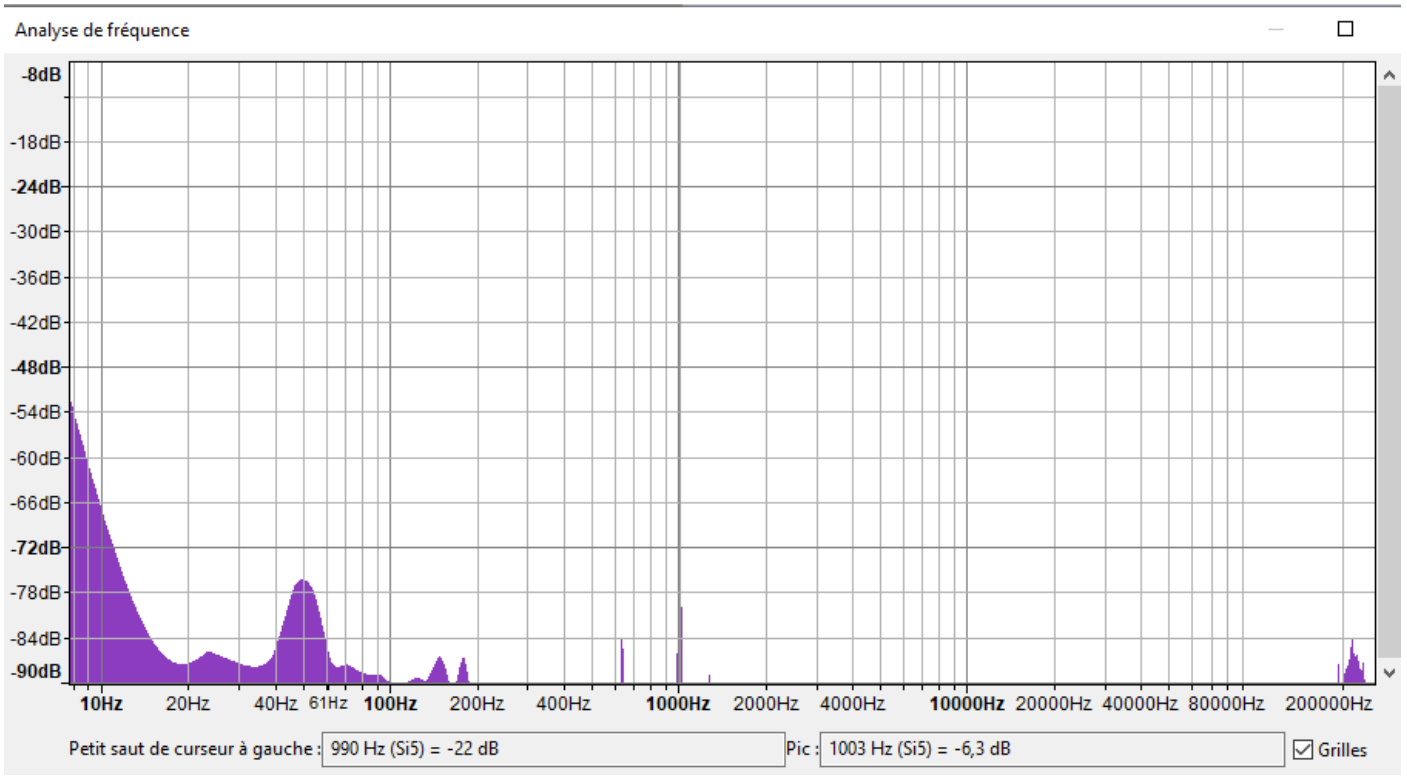
Pure sine 20mV F=1kHz

Gain X50

Waveform and spectrogram



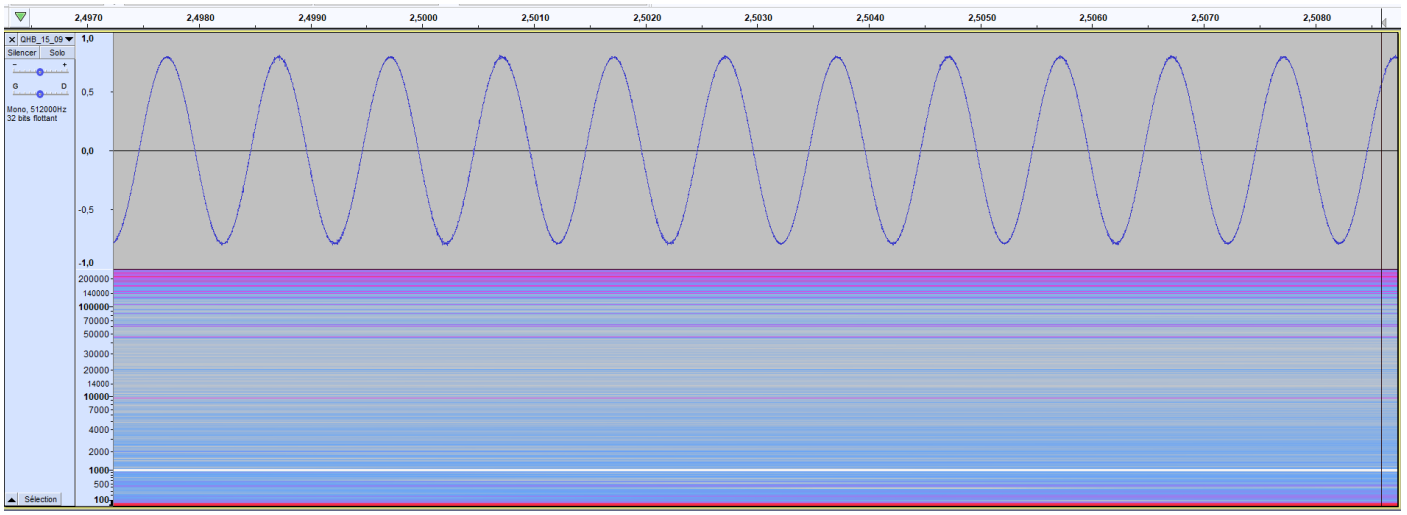
Spectrum



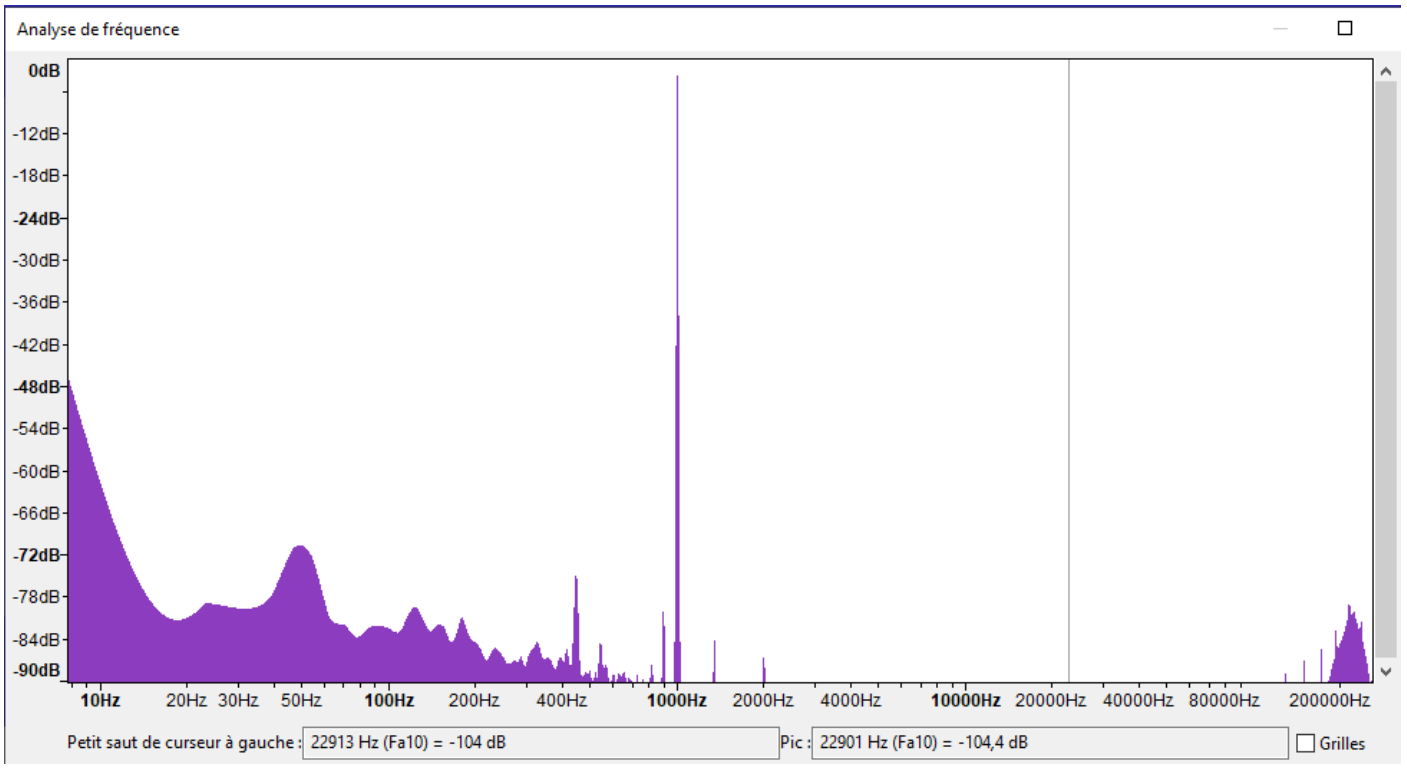
Noise level below **-110dB**

Gain X100

Waveform and spectrogram



Spectrum



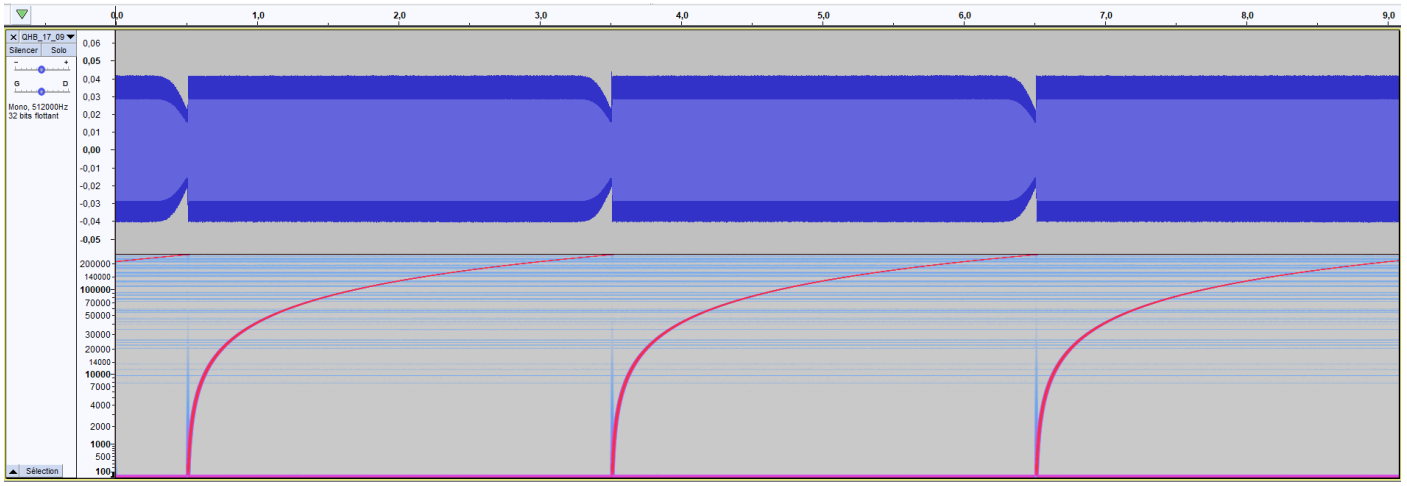
Noise level below **-104dB**

Single Ended - Sweep Input

Sweep sine 100mV F=1Hz to 256kHz

Gain X1

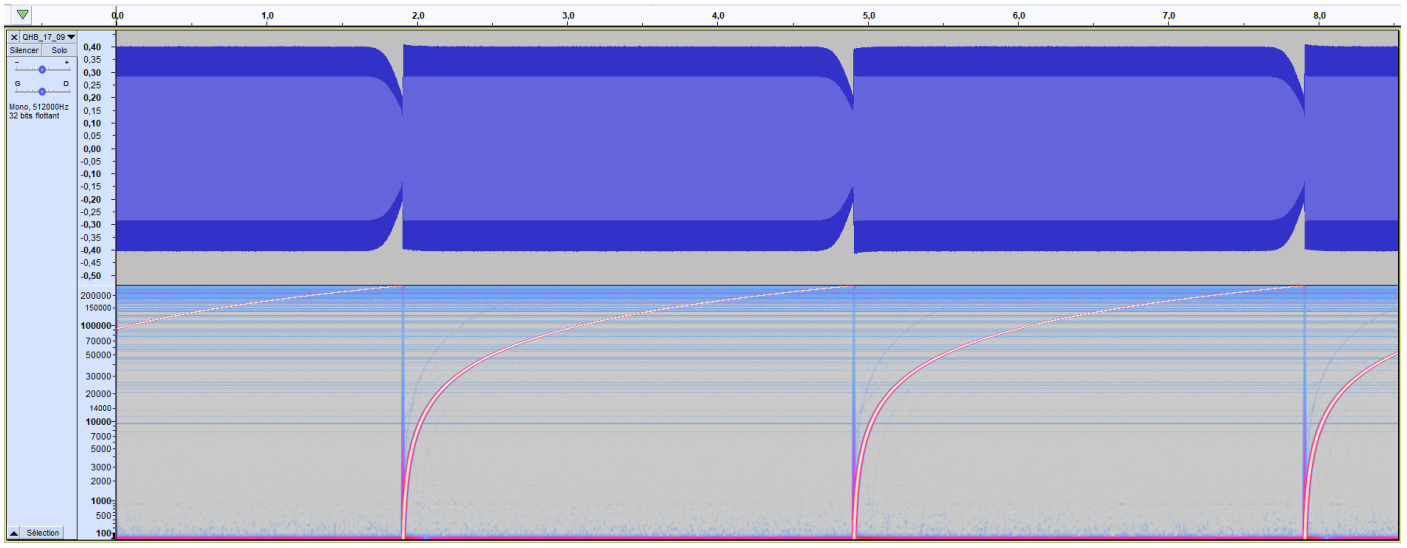
Waveform and spectrogram



In x1 mode and with a sampling frequency of 512ksps, gain is constant for all input frequencies in a range going from 1Hz to 230kHz. An attenuation happens after (up to 50% at max signal frequency).

Gain X10

Waveform and spectrogram

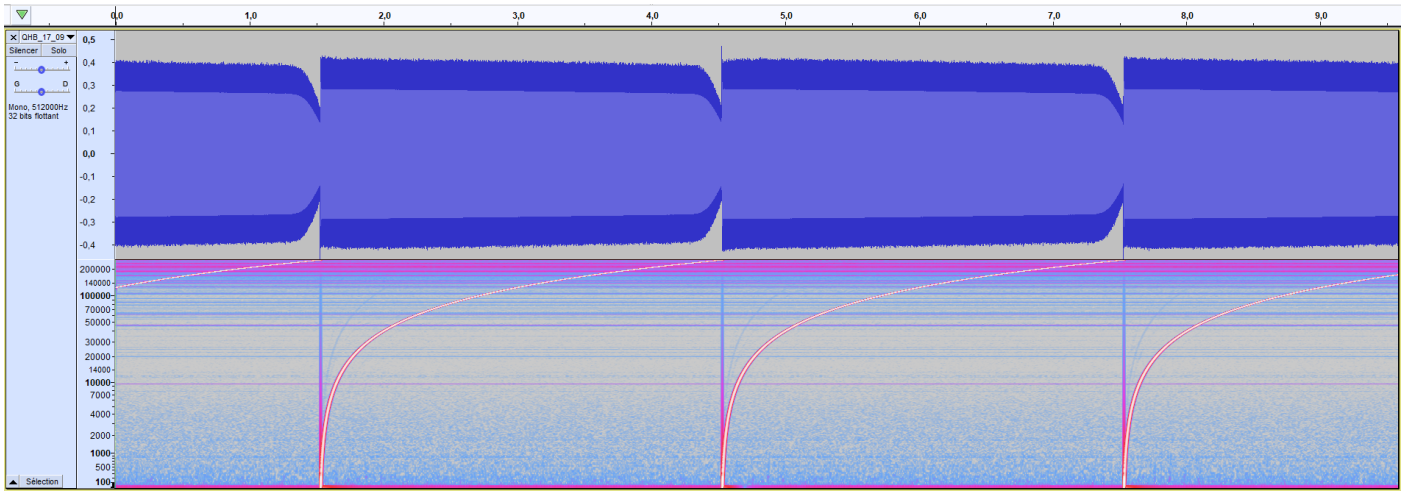


In x10 mode and with a sampling frequency of 512ksps, gain is constant for all input frequencies in a range going from 1Hz to 230kHz. An attenuation happens after (up to 50% at max signal frequency).

Sweep sine 20mV F=1Hz to 256kHz

Gain X50

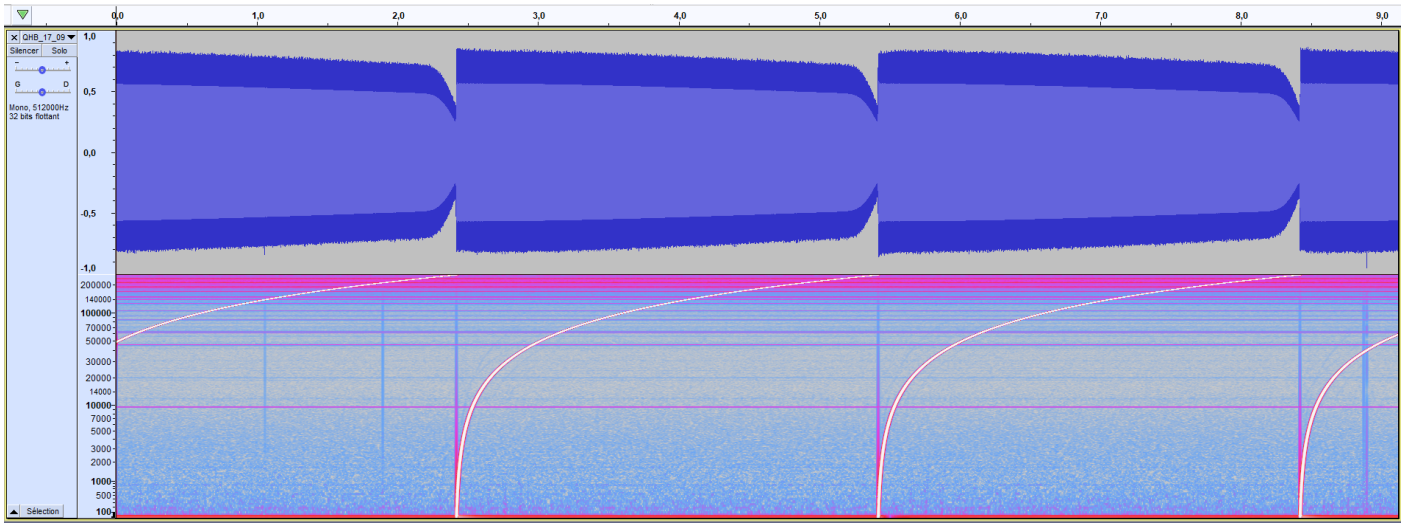
Waveform and spectrogram



In x50 mode and with a sampling frequency of 512ksps, gain is close to be constant for all input frequencies in a range going from 1Hz to 230kHz. An attenuation happens after (up to 50% at max signal frequency).

Gain X100

Waveform and spectrogram



In x100 mode and with a sampling frequency of 512ksps, gain is close (a progresive attenuation of less than 15% happens as frequency increases) to be constant for all input frequencies in a range going from $1Hz to 230kHz. An attenuation happens after (up to 50% at max signal frequency).

CHECK-LIST

- Check the uSD is correctly set.
- Check the batteries are fully charged and properly placed.
- Check that the switch or jumper is in place.

FAQ

GUARANTEE

SMIoT is not responsible for leakage or immersion inside the tube.If damaged, spare O-rings are provided, or available on request to SMIoT within 15 days if necessary. It is impossible that leakage can occur unless the above instructions are not followed.

REMARKS / MISCELLANEOUS

INFORMATION ON THE STATUS OF LEDS:

We advise you to check the status of the LEDs to detect any false manipulation

The LED **GREEN** indicates that the system has recognized the MSD device, and is ready to start acquisitions.
The LED **ORANGE** indicates that the system is being recorded.
Finally, the LED **RED** indicates a potential problem: permanently lit: critical error (fatal error).

FUSE REPLACEMENT:

A protection fuse is present on the QHB. It prevents QHB from being damaged in case of overcurrent.

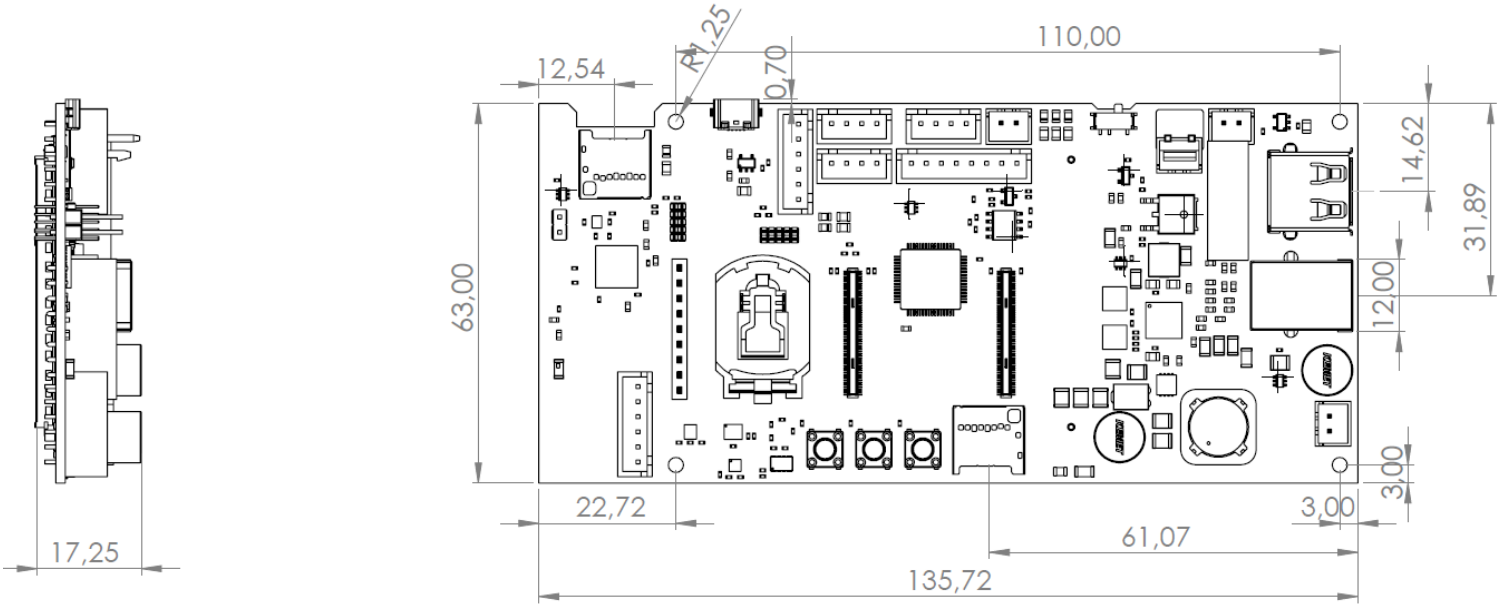
It has to be 2A Max.

NOTES:

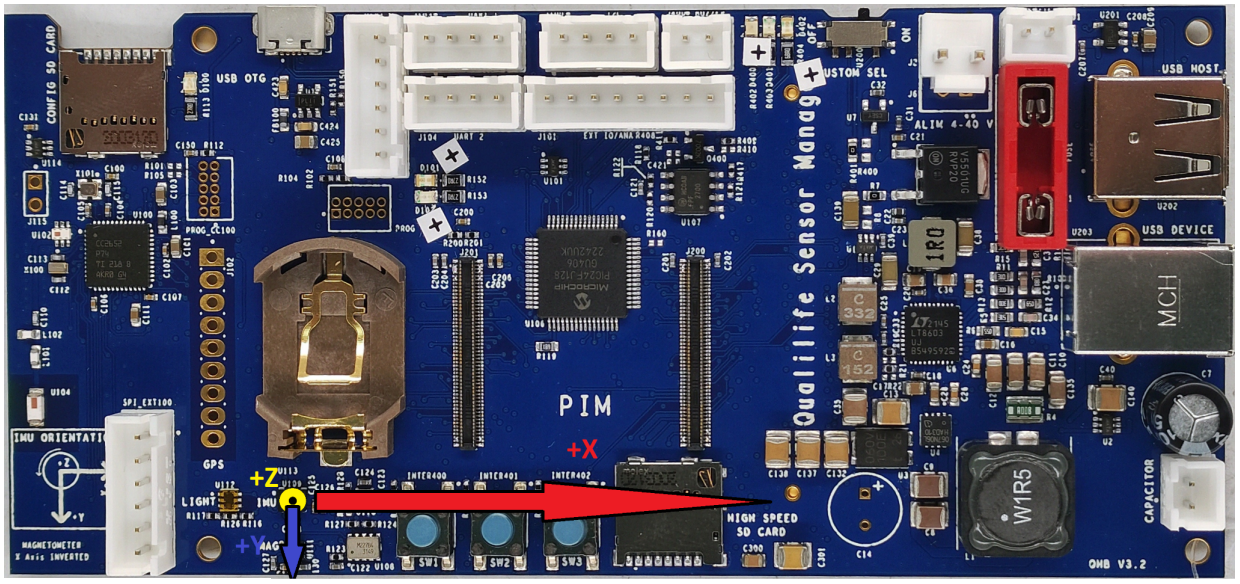
The storage medium is **mandatory** in the case of stand-alone operation. If a system error in this case, restart the system.

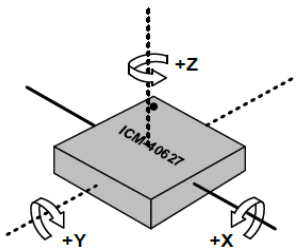
Mechanical Information

QHB Motherboard V3.1 drawing

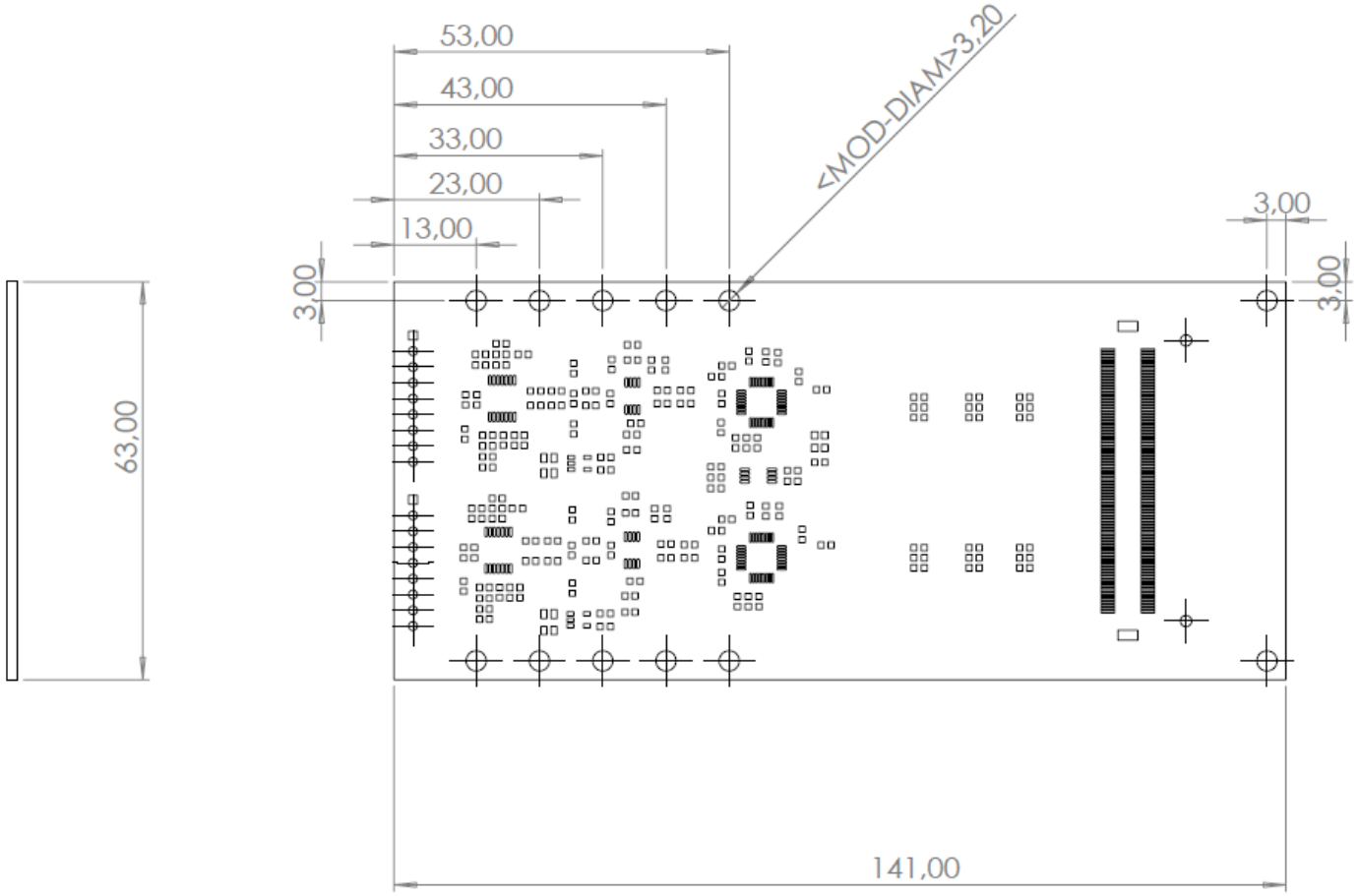


Orientation of Axes (IMU)

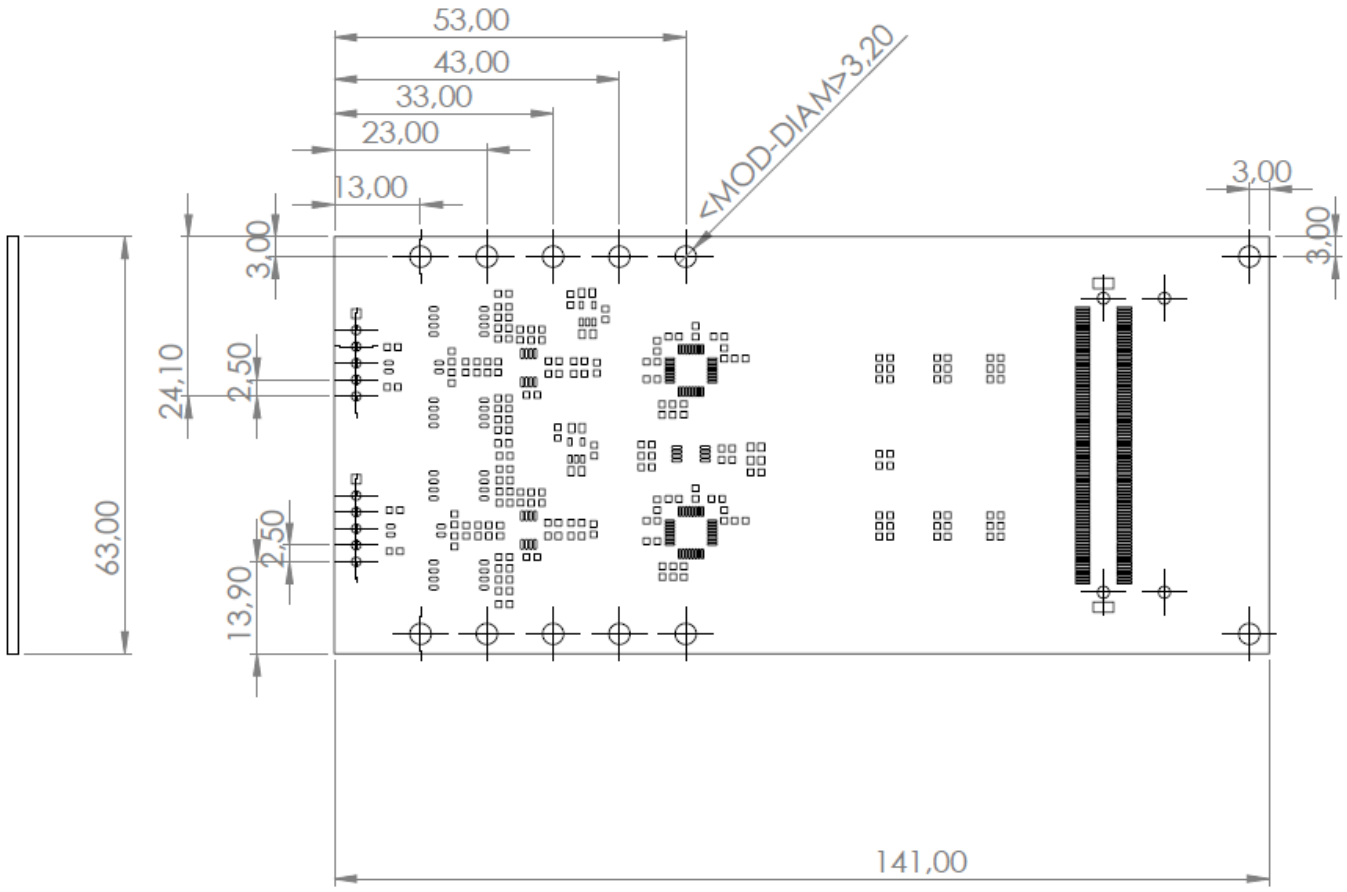




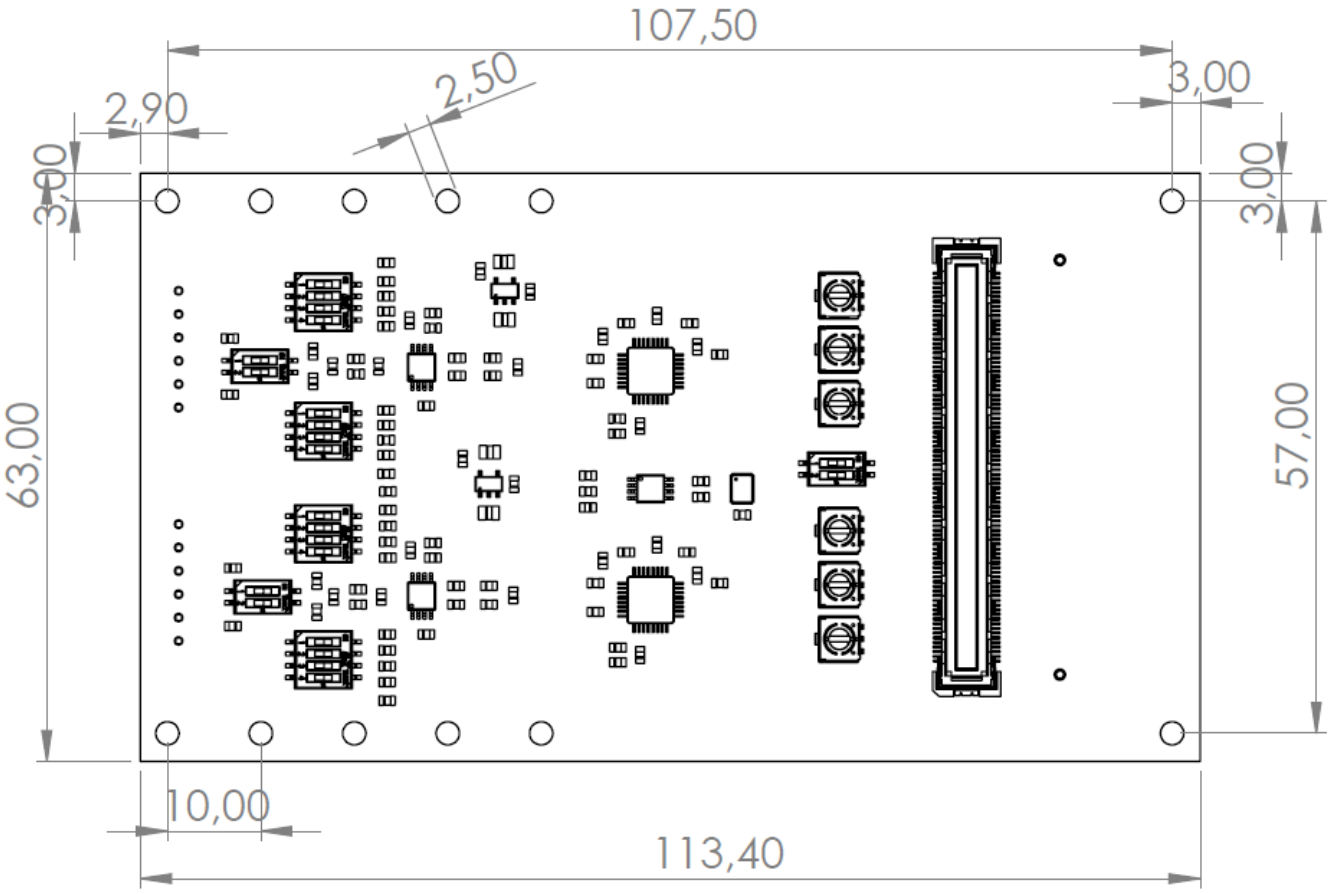
QHB Daughter board V2 drawing



QHB Daughter board V3 Drawing



QHB Daughter board V3.1 Drawing



CONTACT US

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